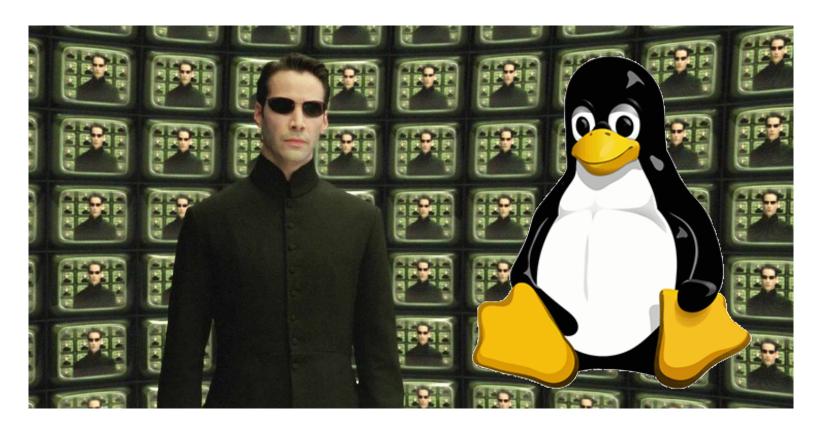
#### **CSCI 125** Introduction to Computer Science and **Programming II** Lecture 7: Data Structure IV

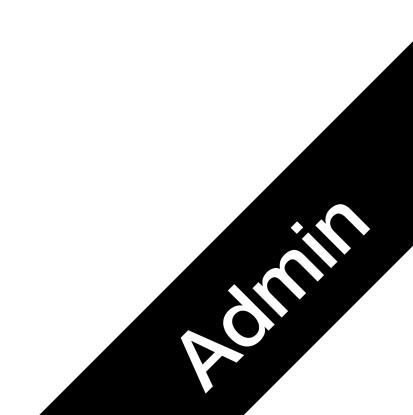


Jetic Gū 2020 Summer Semester (S2)



- Assignment 4 and Lab 4 due 9 Aug, covering Lecture 7
- No class next Monday (BC day)
- Last batch of OJ problem: 6 problems p025-p030

# Some changes



#### Overview

- Focus: Data Structures
- Architecture: Linux/Unix OS
- Core Ideas:
  - 1. Breath-First Search VS Depth-First Search



# Search Algorithms

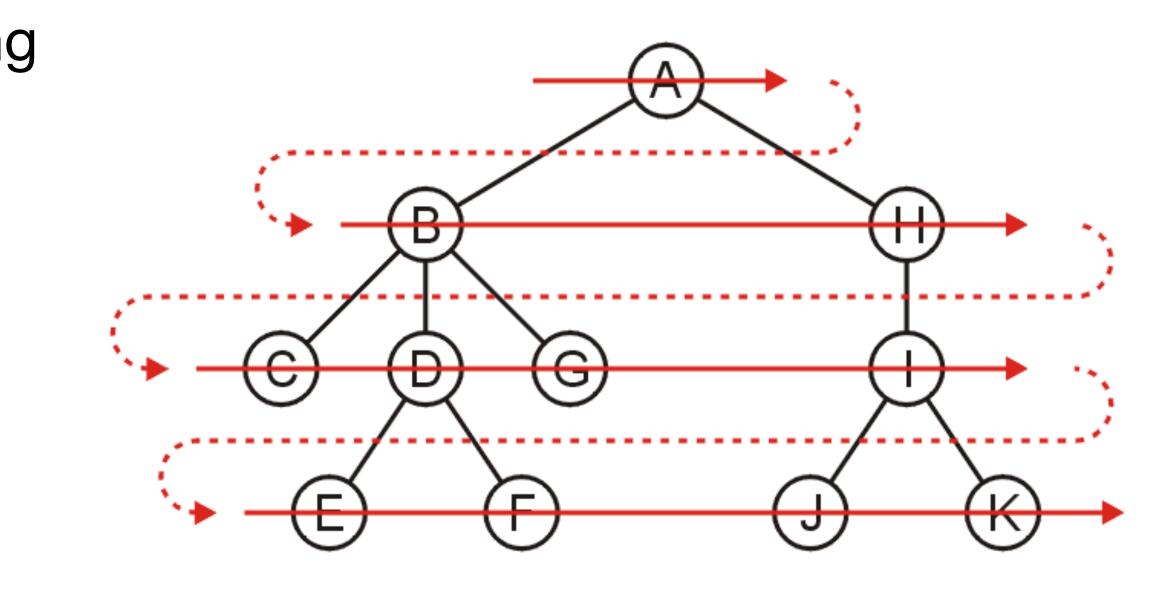
Breath-First Search VS Depth-First Search





#### **Breath-First Search**

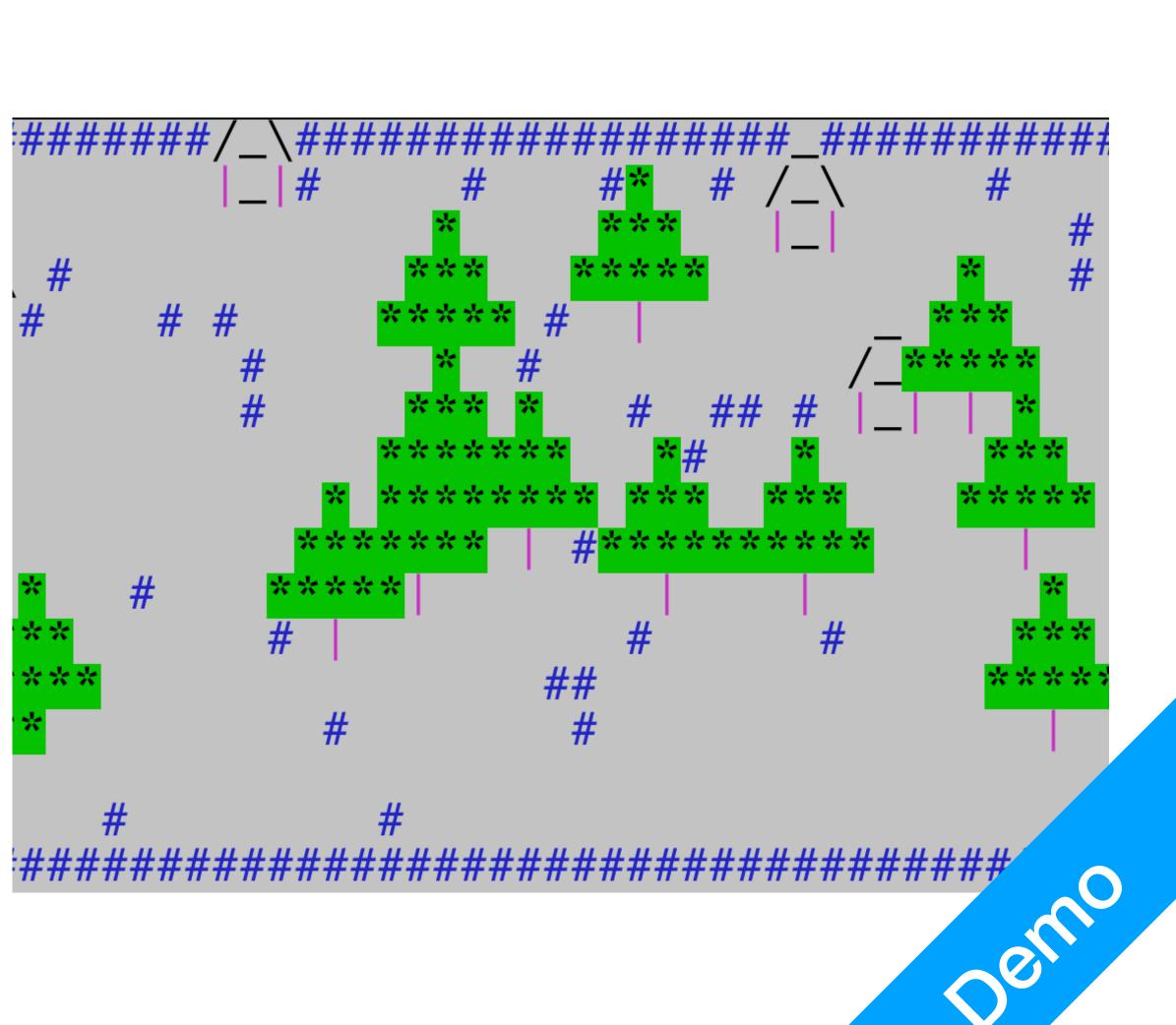
- Algorithm for traversing or searching
- Visit all nodes on the same depth, before moving on
  - Implementation using Queue
  - Works on trees and graphs







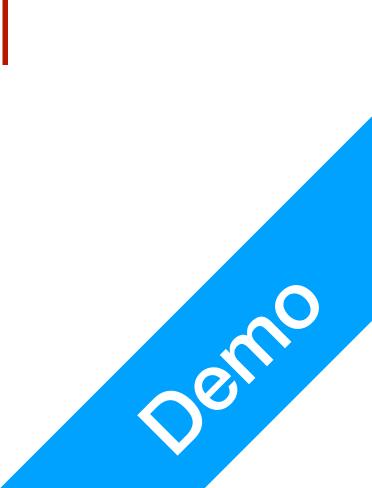
- Village of the Sorcerer
  - Certain areas of the map are not reachable (fences, houses)
  - Certain areas might be entirely blocked off by fences



#### P1 Searching

# **BFS Example**

- Village of the Sorcerer
  - Certain areas of the map are not reachable (fences, houses)
  - Certain areas might be entirely blocked off by fences
  - +: player



#### **P1** Searching

# BFS Example

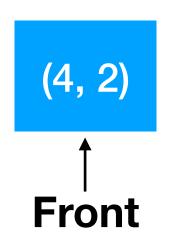
- Village of the Sorcerer
  - Certain areas of the map are not reachable (fences, houses)
  - Certain areas might be entirely blocked off by fences
  - +: player
  - Light Red: player accessible regions

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- We start by initialising a Queue to st coordinates
- push(playerCoordinate), which is 4,2
  - push((4,2));
  - In C++, you can simulate this using int-based queues

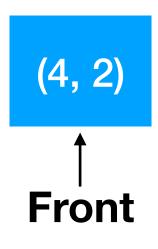


tore		0	1	2	3	4
2	0	*	#			
	1	#	#	#	#	#
	2	#		#		#
ng 2	3	#		#		#
	4	#		╉		#
	5		#		#	





**P1** Searching



1. P030

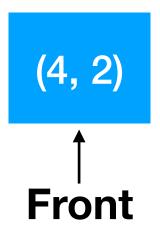
	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
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• For every frontal element, push it's neighbouring reachable coordinates, and mark itself as visited

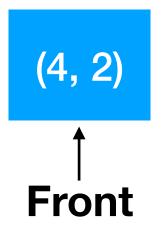


	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		╉		#
5		#		#	





• front() = 
$$(4, 2);$$



	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	



**P**1 Searching

- For every frontal element, push it's neighbouring reachable coordinates, and mark itself as visited
  - front() = (4, 2);
  - push(4,1); push(4,3); push(5,2)

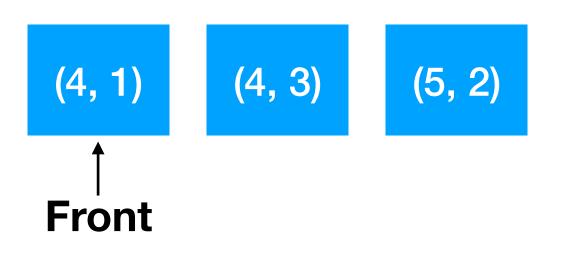


	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	



**P1** Searching

- For every frontal element, push it's neighbouring reachable coordinates, and mark itself as visited
  - front() = (4, 2);
  - push(4,1); push(4,3); push(5,2)
  - pop();



	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	



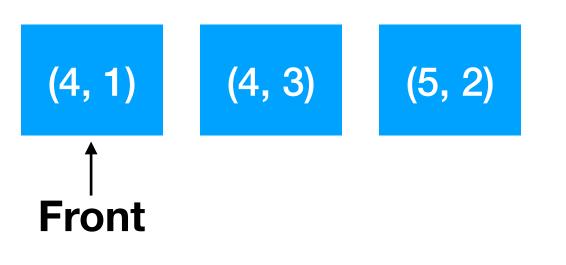
P1 Searching



	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	







	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	



• front() = 
$$(4, 1);$$

	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	



• front() = 
$$(4, 1);$$

	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	

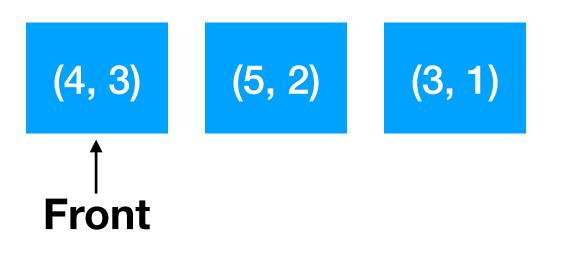


• For every frontal element, push it's neighbouring reachable coordinates, and mark itself as visited

• front() = 
$$(4, 1);$$

• push(3,1);

• pop();



	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	



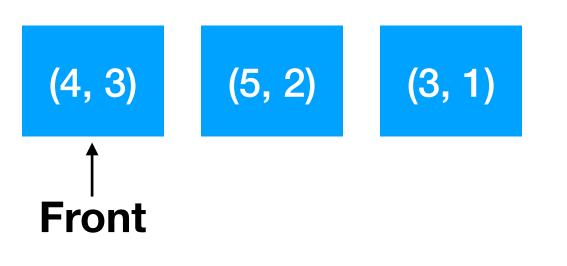
P1 Searching



	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	



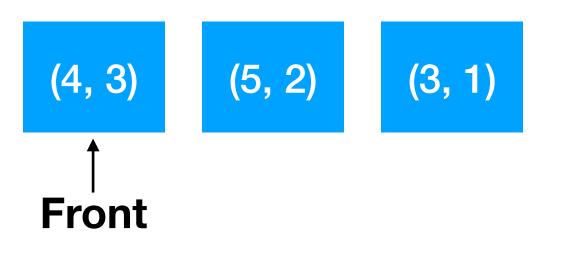




	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	



• front() = 
$$(4, 3);$$



	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	



• front() = 
$$(4, 3);$$

	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	

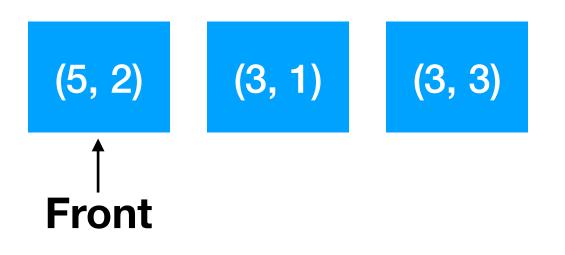


• For every frontal element, push it's neighbouring reachable coordinates, and mark itself as visited

• front() = 
$$(4, 3);$$

• push(3,3);

• pop();



	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	



P1 Searching

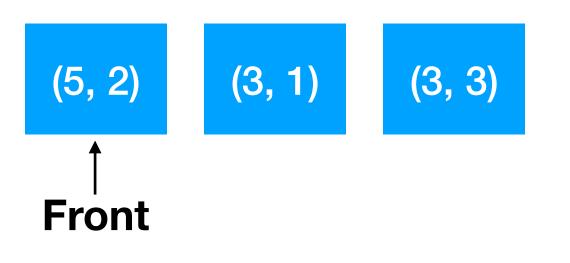


1. P030

	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	







	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	



• front() = 
$$(5, 2);$$



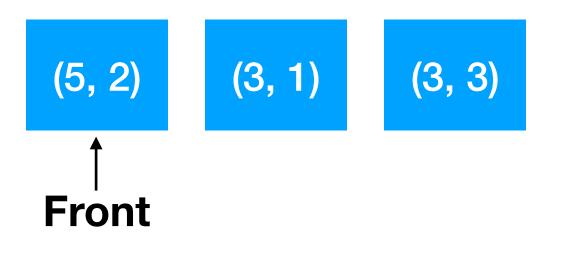
	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	



• For every frontal element, push it's neighbouring reachable coordinates, and mark itself as visited

• front() = 
$$(5, 2);$$

• no push here

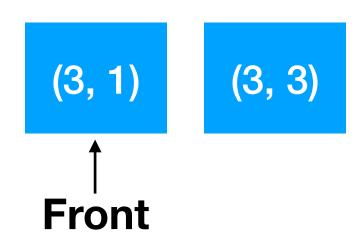


	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	



• front() = 
$$(5, 2);$$

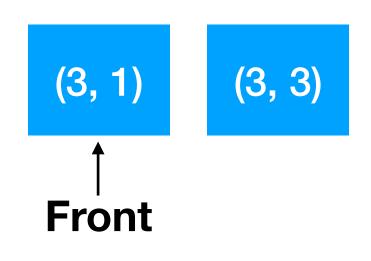
- no push here
- pop();



	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	

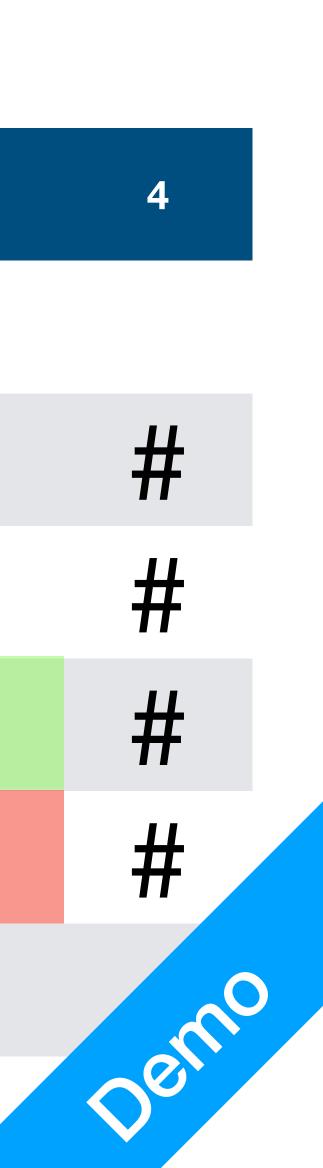


P1 Searching



1. P030

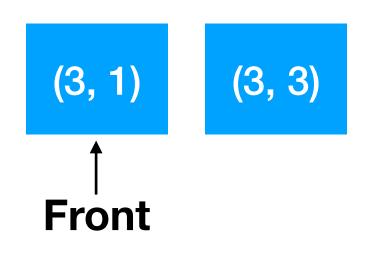
	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	







• For every frontal element, push it's neighbouring reachable coordinates, and mark itself as visited



	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	



• front() = 
$$(3, 1);$$

	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	



• front() = 
$$(3, 1);$$

	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	

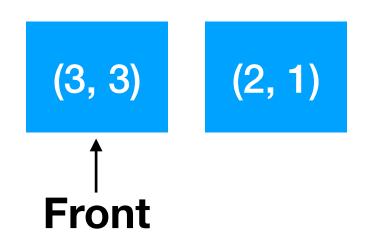


• For every frontal element, push it's neighbouring reachable coordinates, and mark itself as visited

• front() = 
$$(3, 1);$$

• push(2,1);

• pop();

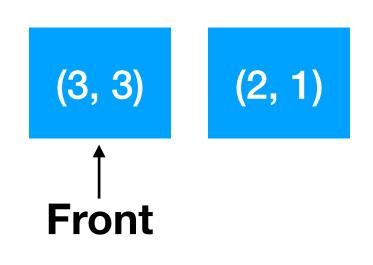


	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	



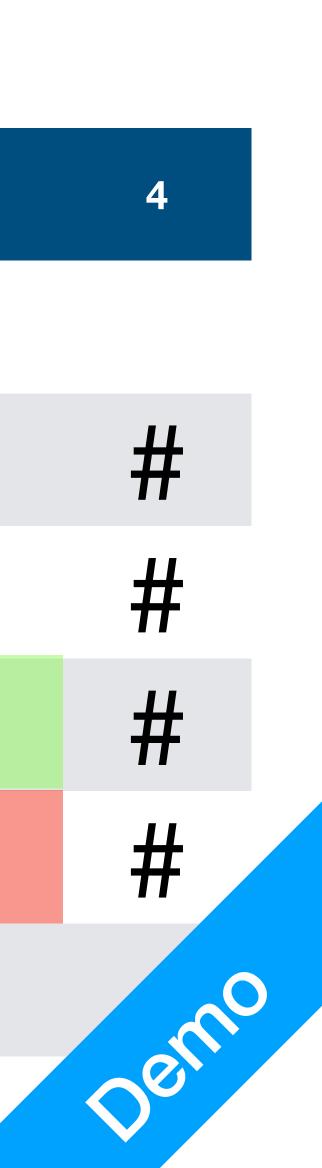


**P1** Searching



1. P030

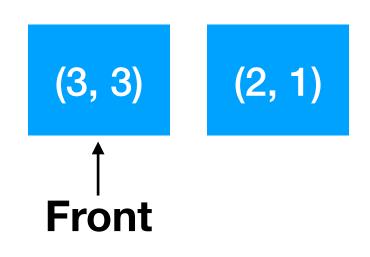
	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
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• For every frontal element, push it's neighbouring reachable coordinates, and mark itself as visited



	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	



• front() = 
$$(3, 3);$$

	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	



• front() = 
$$(3, 3);$$

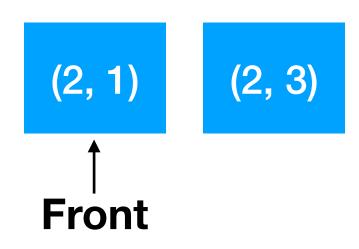


	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	

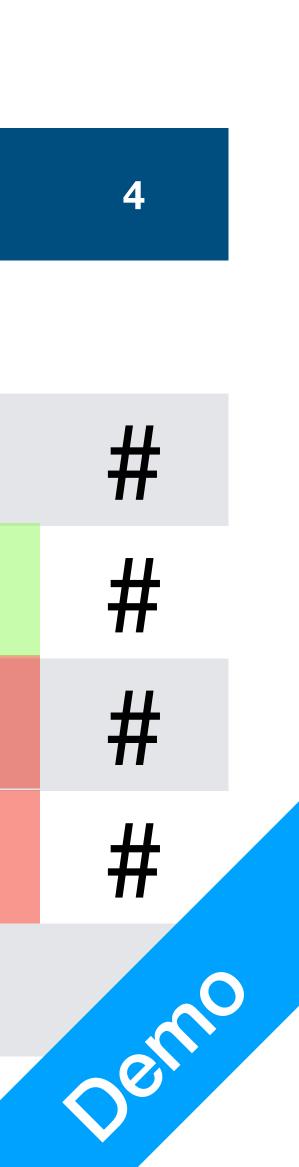


• front() = 
$$(3, 3);$$

- push(2,3);
- pop();

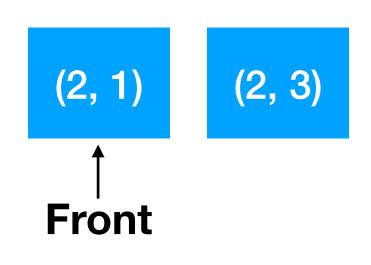


	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	



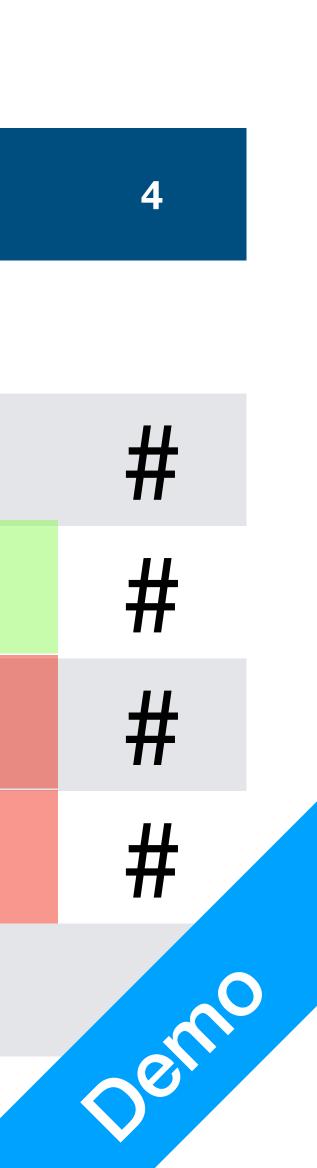


**P1** Searching

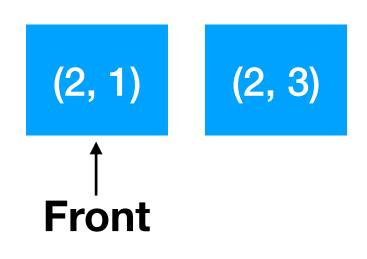


1. P030

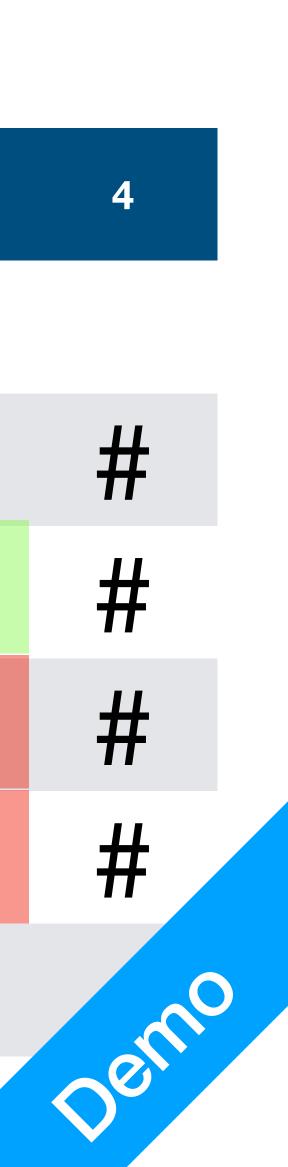
	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	





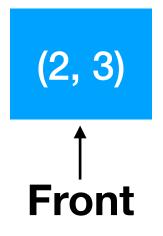


	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	

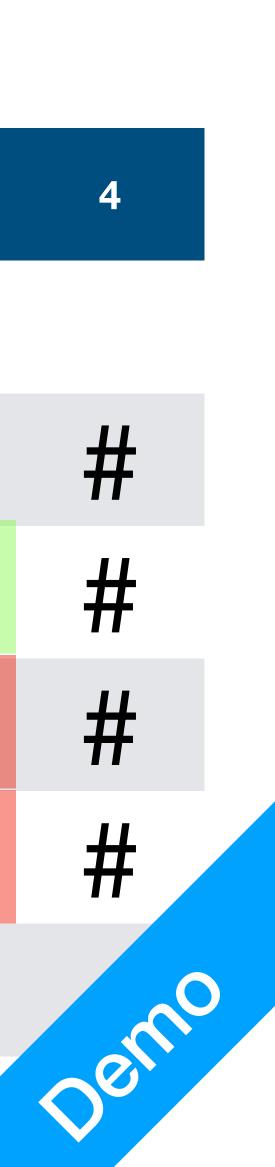


**P1** Searching

- For every frontal element, push it's neighbouring reachable coordinates, and mark itself as visited
  - front() = (2,1); pop();



	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	



#### **P1** Searching

- For every frontal element, push it's neighbouring reachable coordinates, and mark itself as visited
  - front() = (2, 1); pop();
  - front() = (2,3); pop();

	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#		#		#
4	#		+		#
5		#		#	



P1 Searching







#### • Assuming map size $N \times M$ , what is the time and space complexity?







- Assuming map size  $N \times M$ , what is the time and space complexity?
  - Time complexity:  $O(N \times M)$





- Assuming map size  $N \times M$ , what is the time and space complexity?
  - Time complexity:  $O(N \times M)$ 
    - Is it  $\Theta(N \times M)$  as well? Why?



#### **P1** Searching

- Assuming map size  $N \times M$ , what is the time and space complexity?
  - Time complexity:  $O(N \times M)$ 
    - Is it  $\Theta(N \times M)$  as well? Why?
  - Space complexity:  $O(N \times M)$



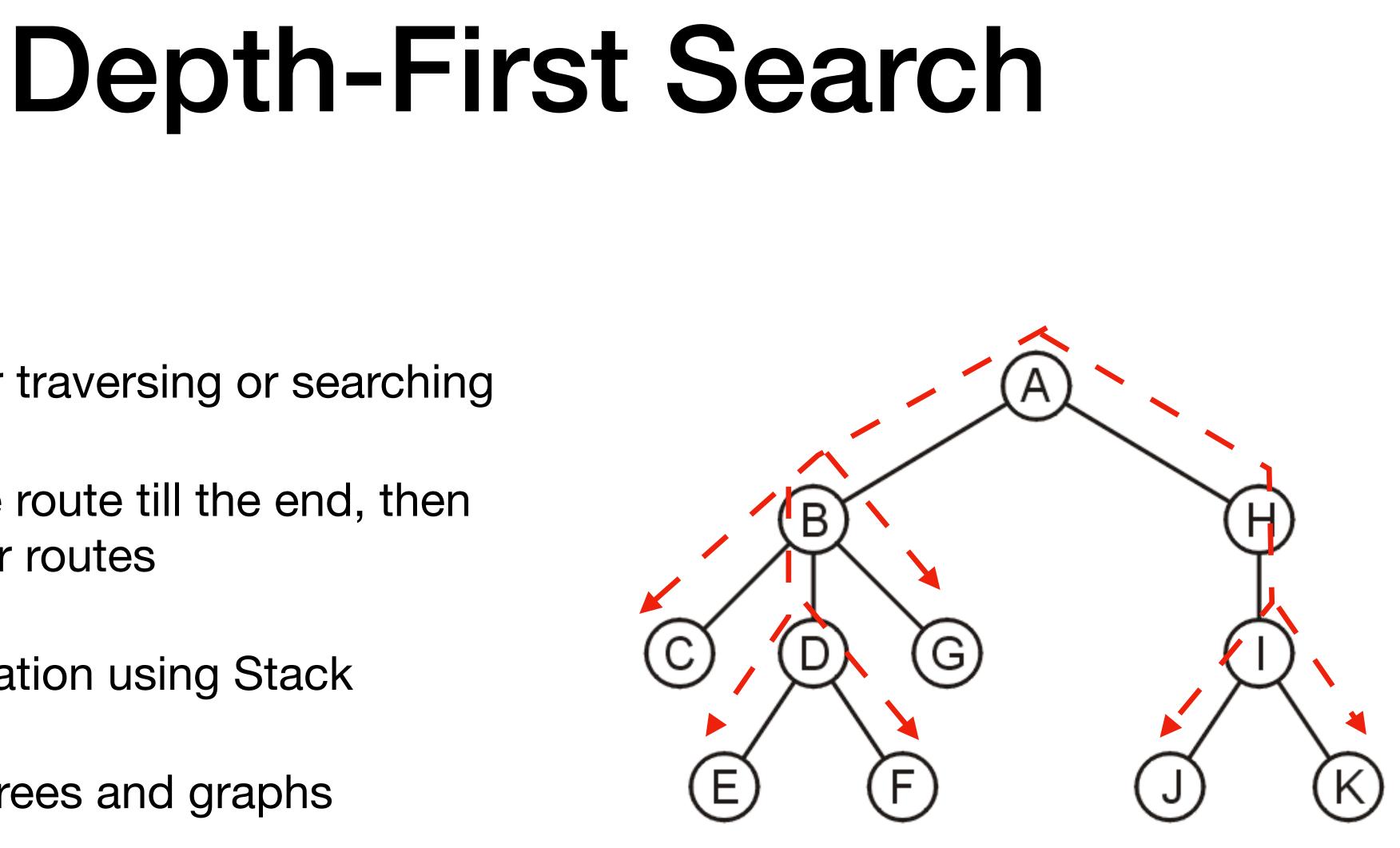
#### **P1** Searching

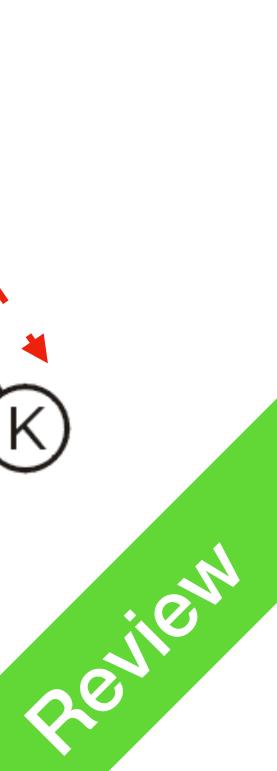
- Assuming map size  $N \times M$ , what is the time and space complexity?
  - Time complexity:  $O(N \times M)$ 
    - Is it  $\Theta(N \times M)$  as well? Why?
  - Space complexity:  $O(N \times M)$ 
    - Is it  $\Theta(N \times M)$  as well? Why?





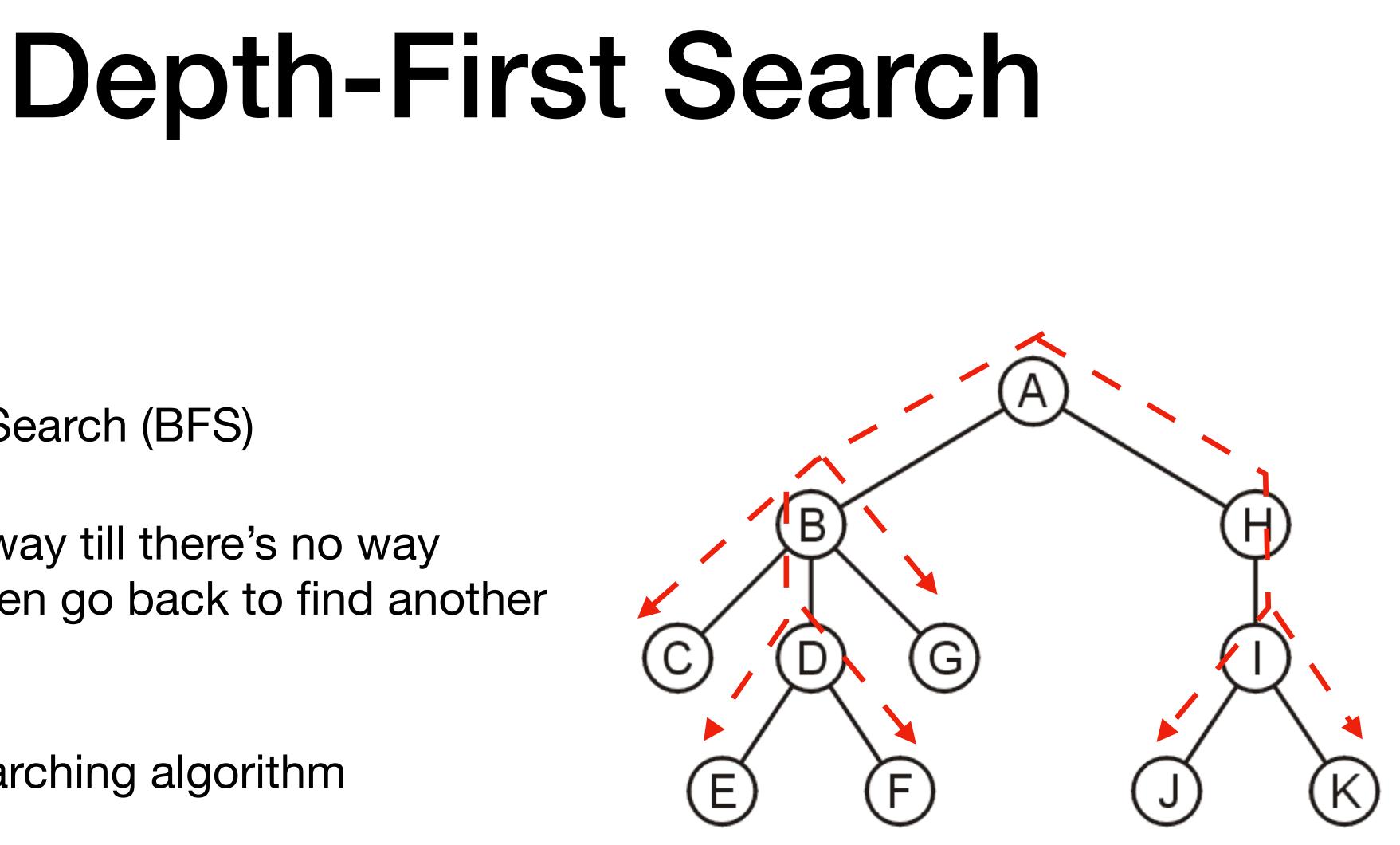
- Algorithm for traversing or searching
- Take a single route till the end, then look for other routes
  - Implementation using Stack
  - Works on trees and graphs

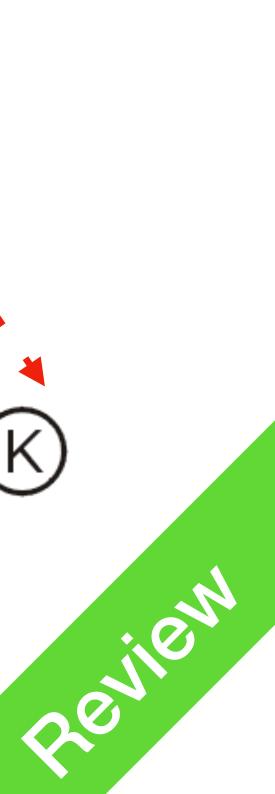






- Depth-First Search (BFS)
  - Go all the way till there's no way forward, then go back to find another way
  - Classic searching algorithm





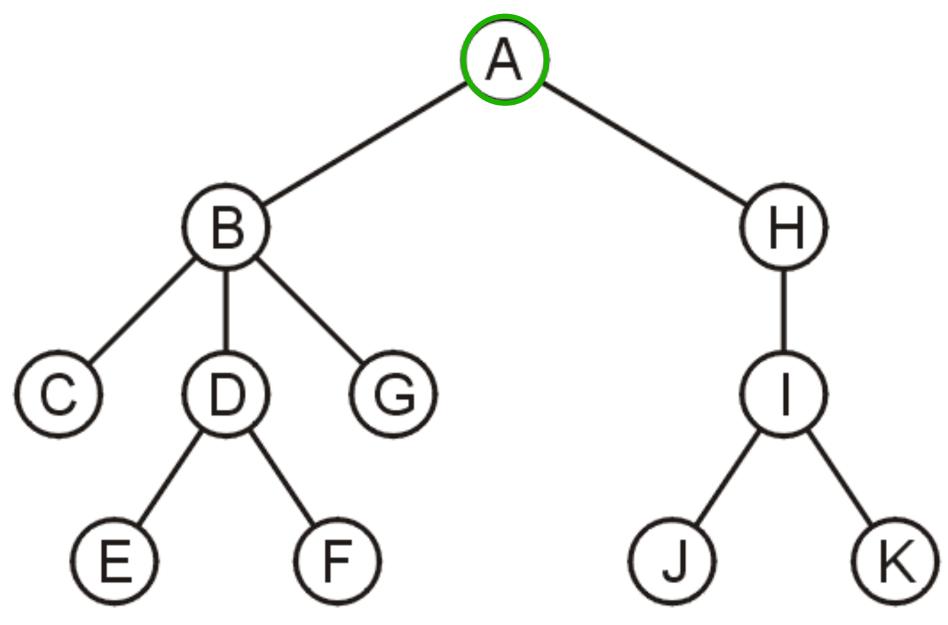


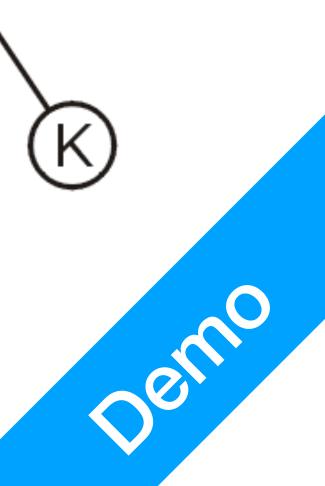


#### • Push the root directory A



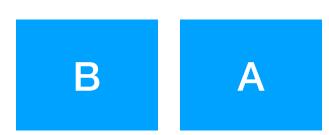
#### **DFS** Tree

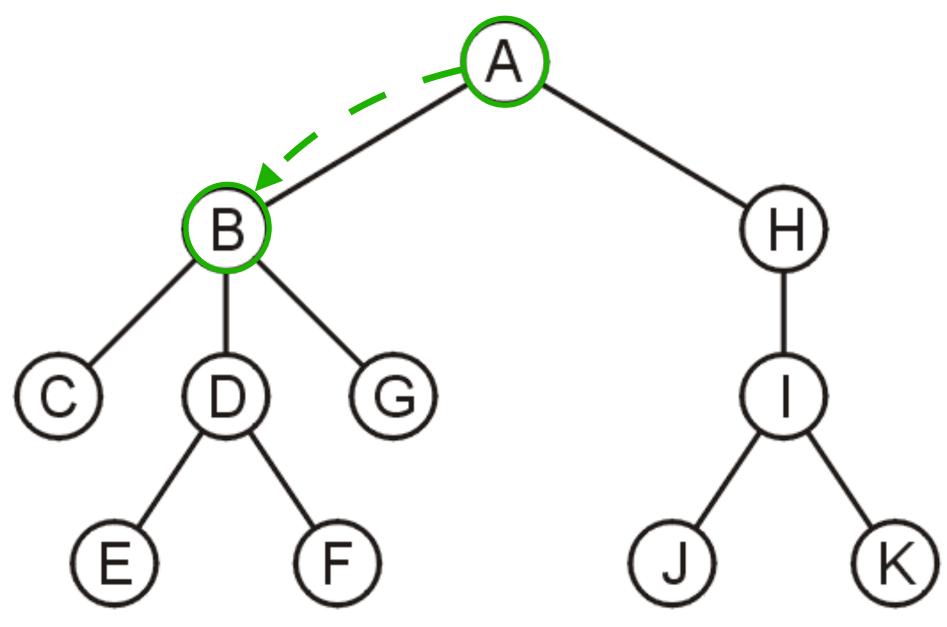


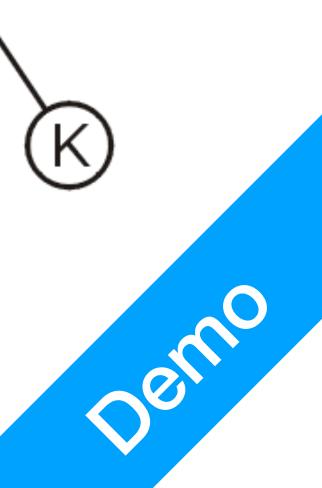




#### • Push B



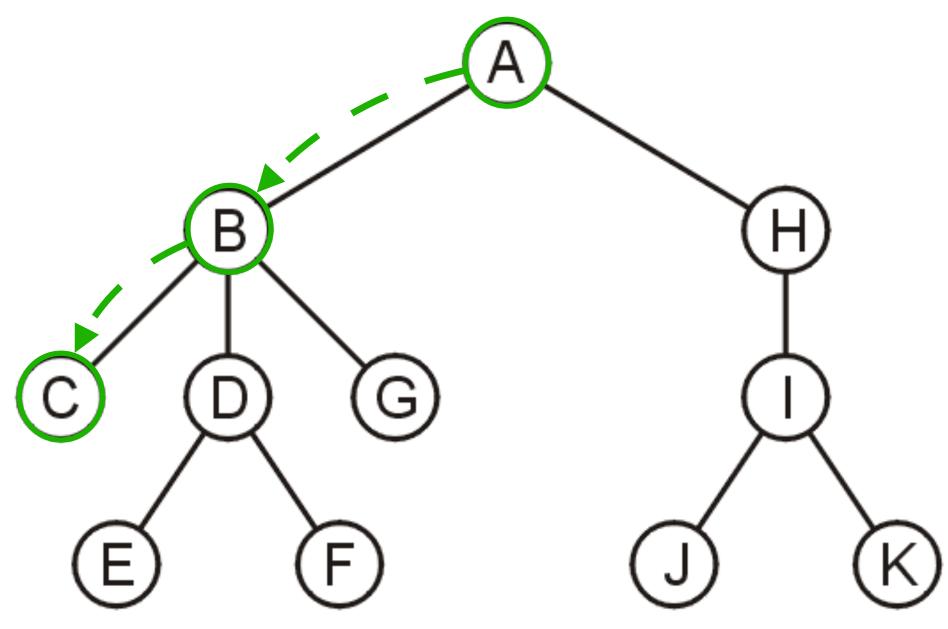


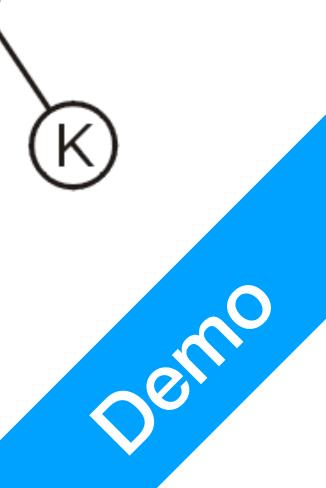




#### • Push C







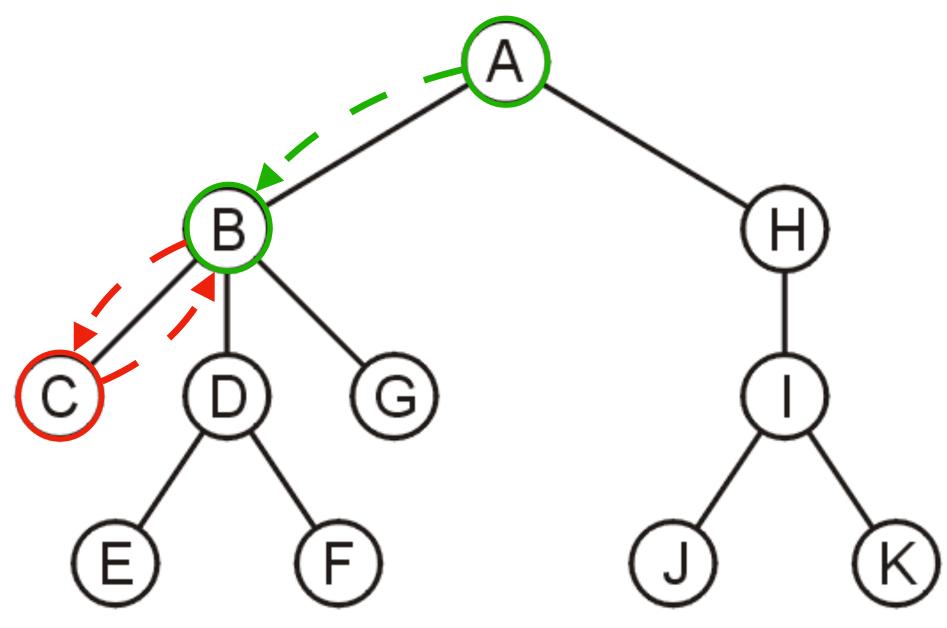


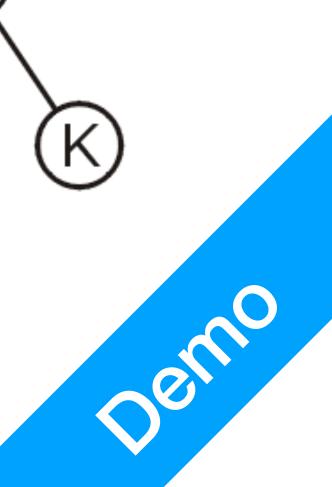


#### • Cannot go any further, pop C



#### **DFS** Tree

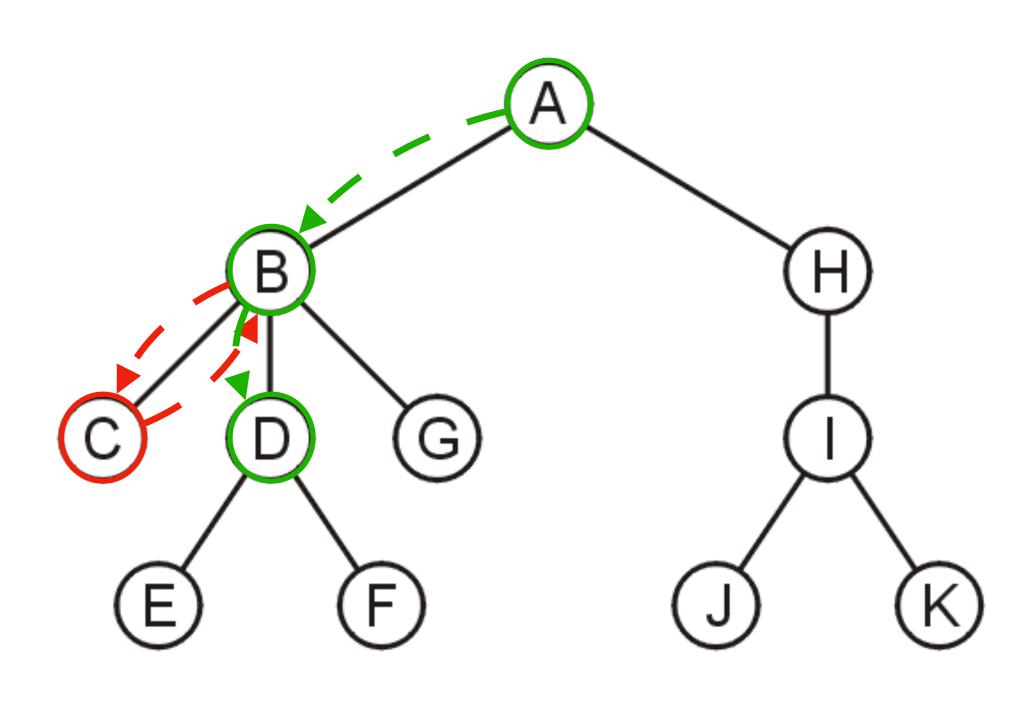


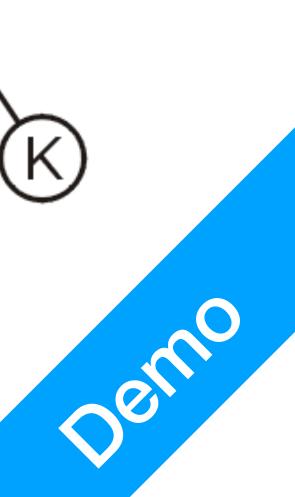




#### • Push D, the next not yet visited child of B



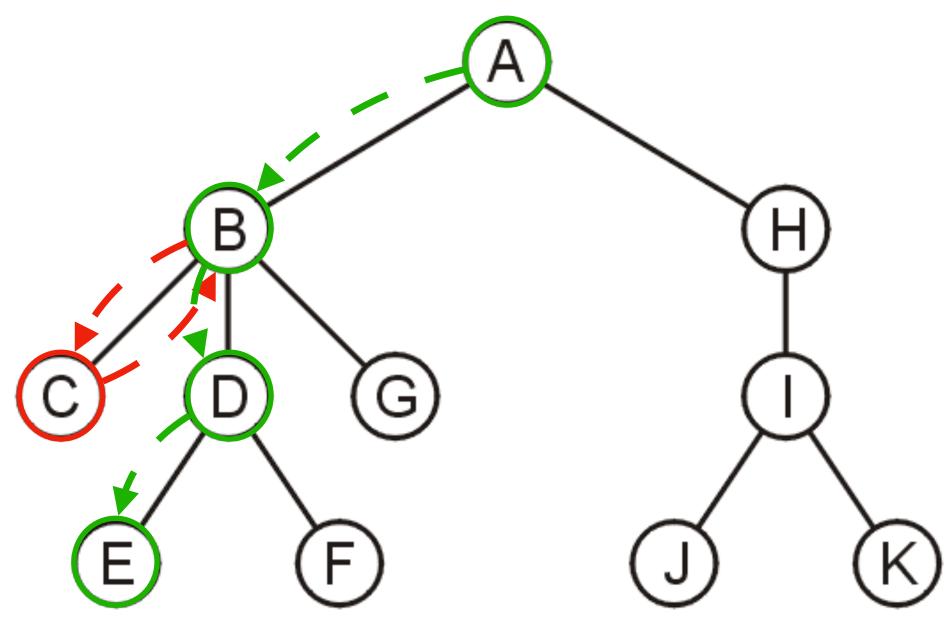


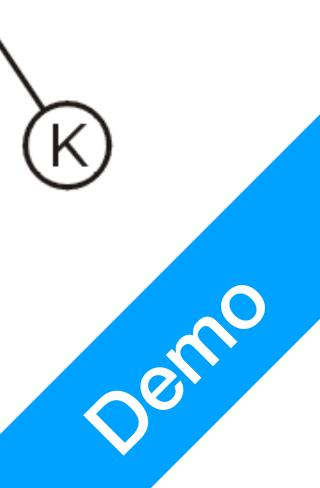




#### • Push E



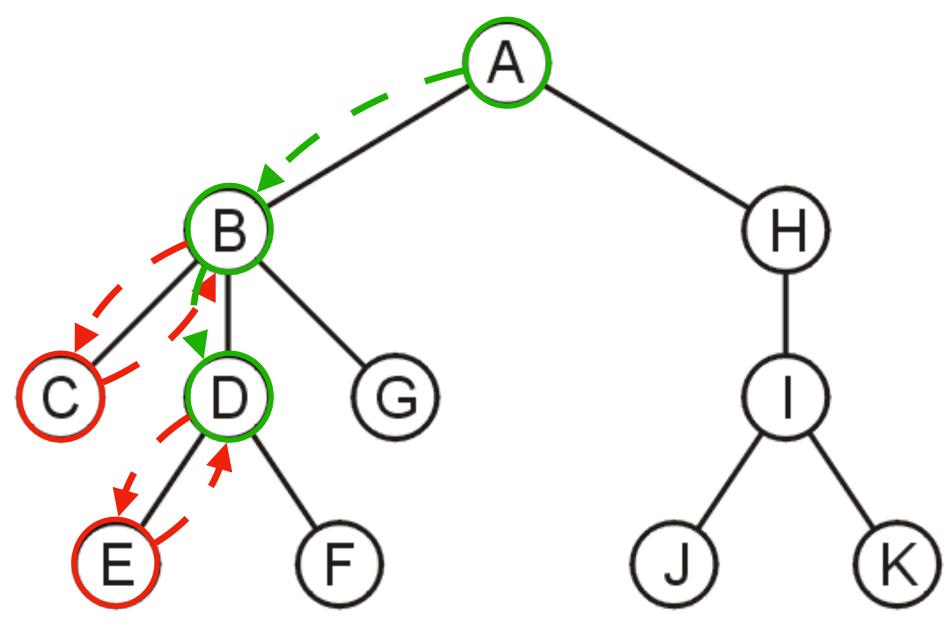


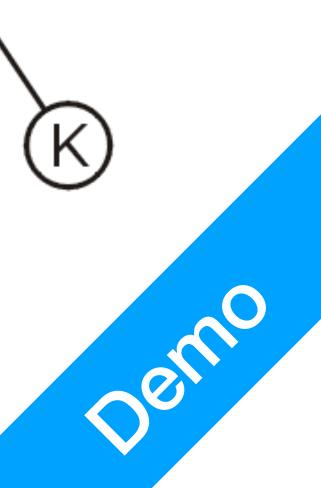




#### • Pop E, go back to D



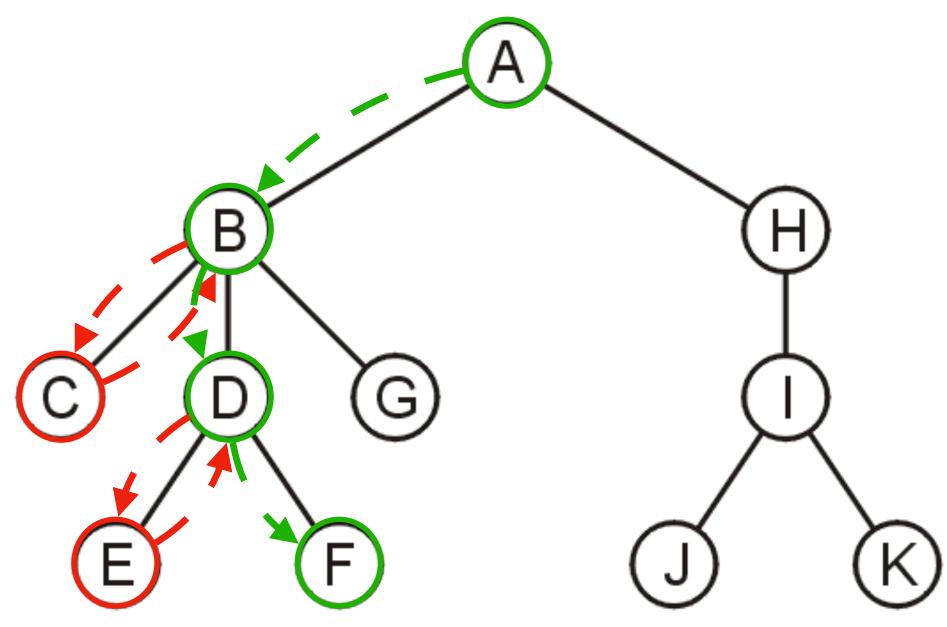


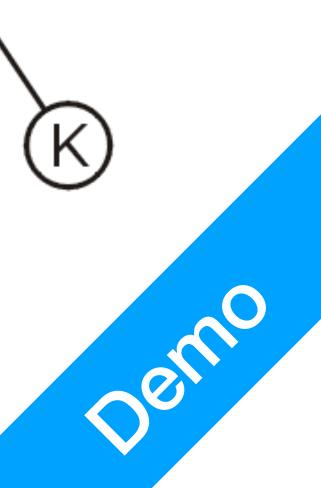




#### • Push F



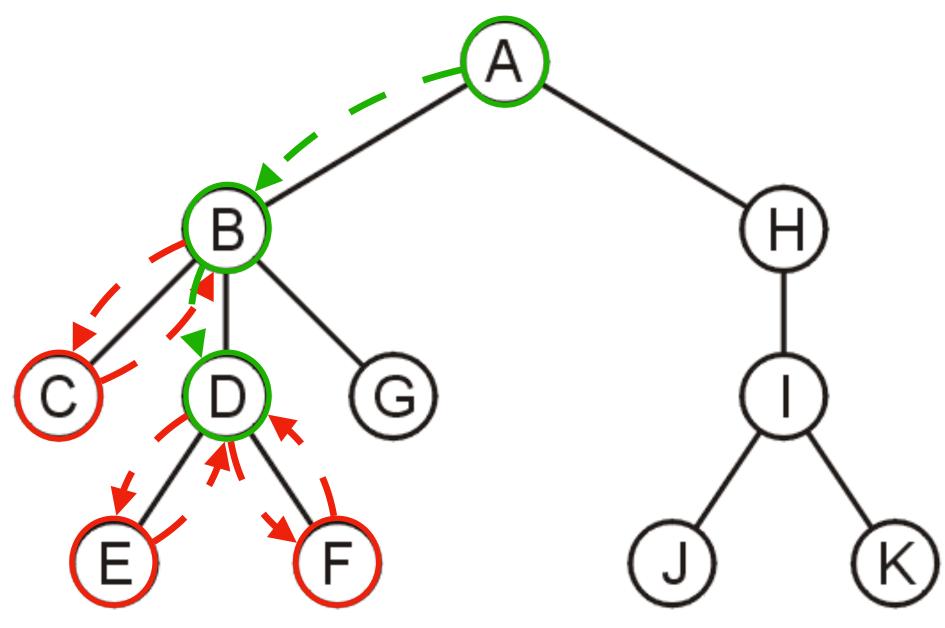


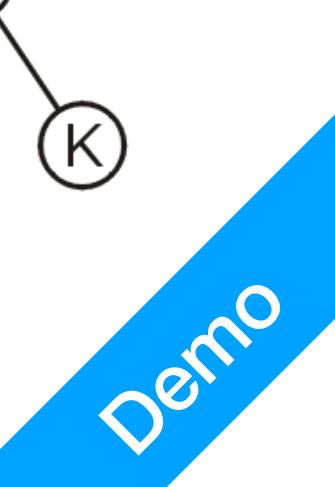




#### • Pop F, go back to D



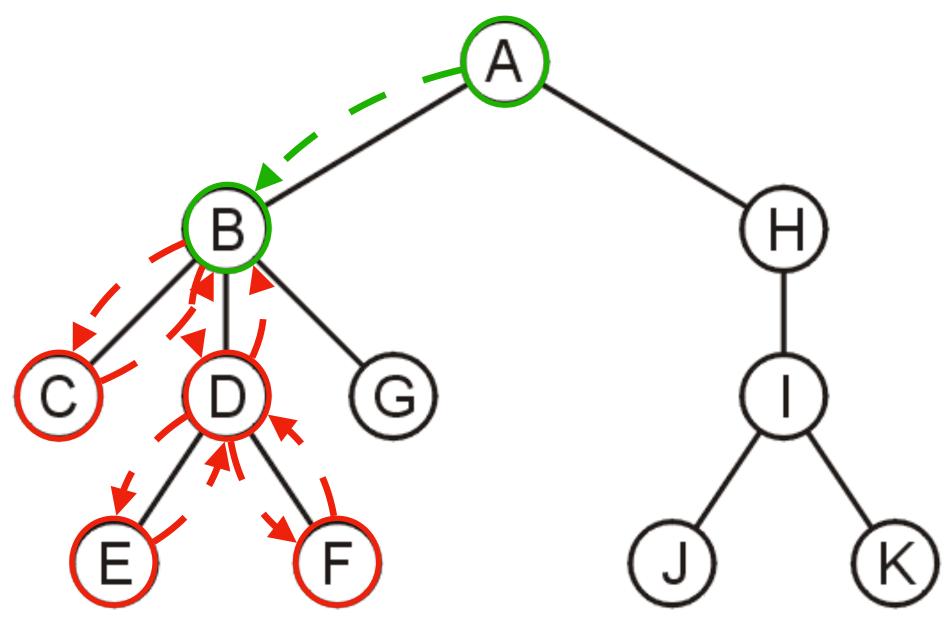


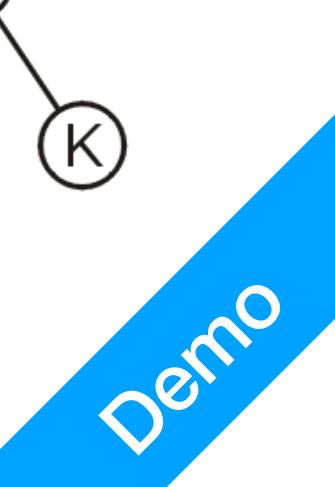




#### • Pop D, go back to B



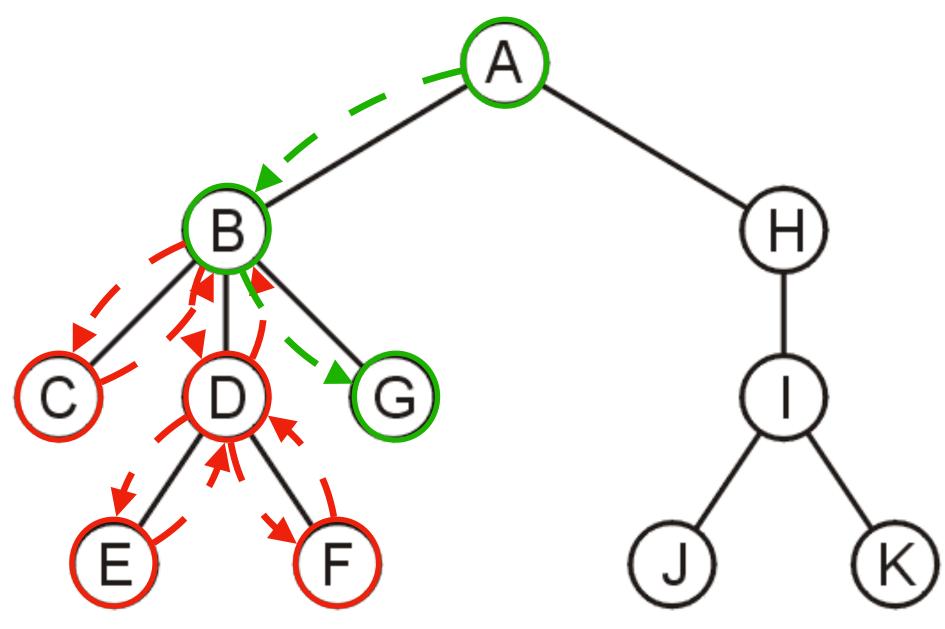


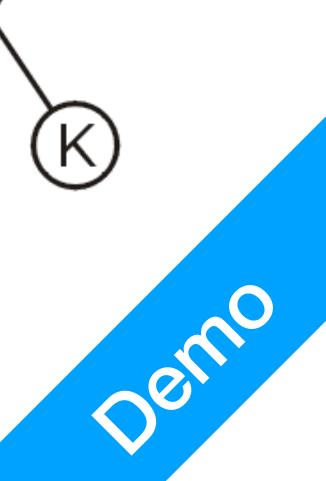




#### • Push G



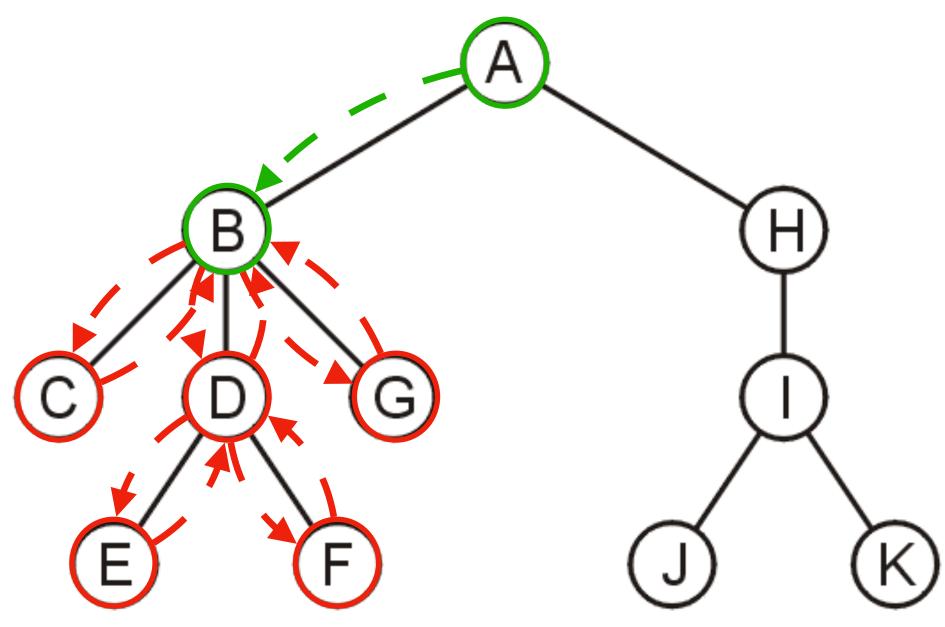


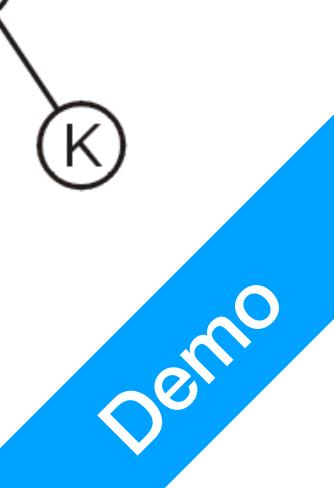




#### • Pop G, go back to B



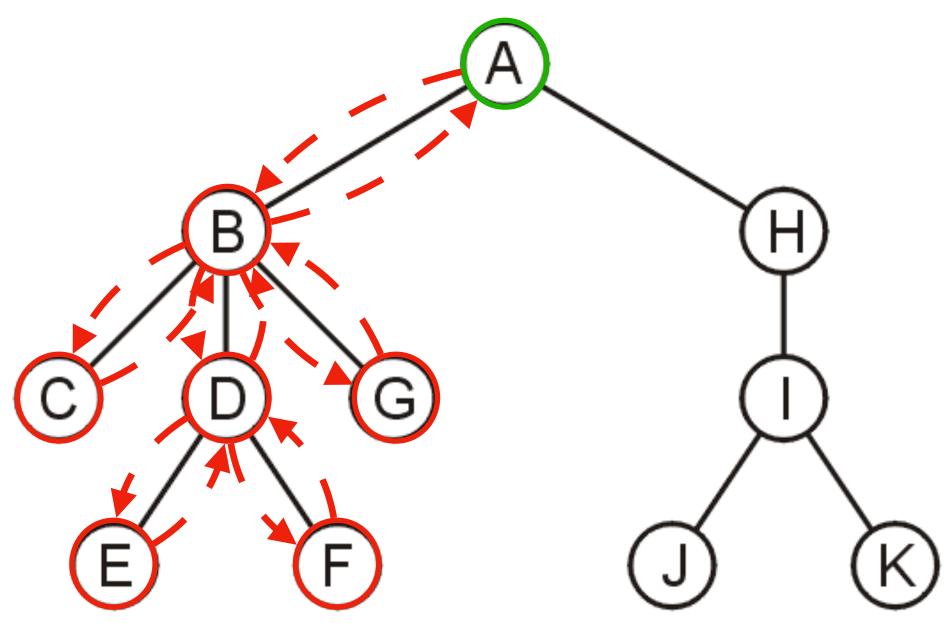


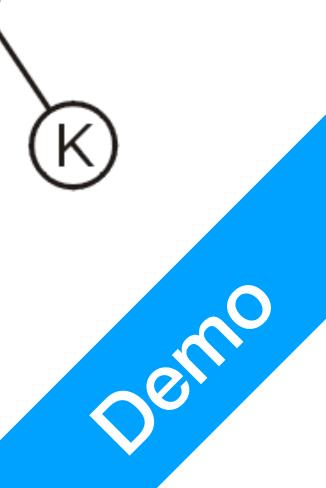




#### • Pop B, go back to A



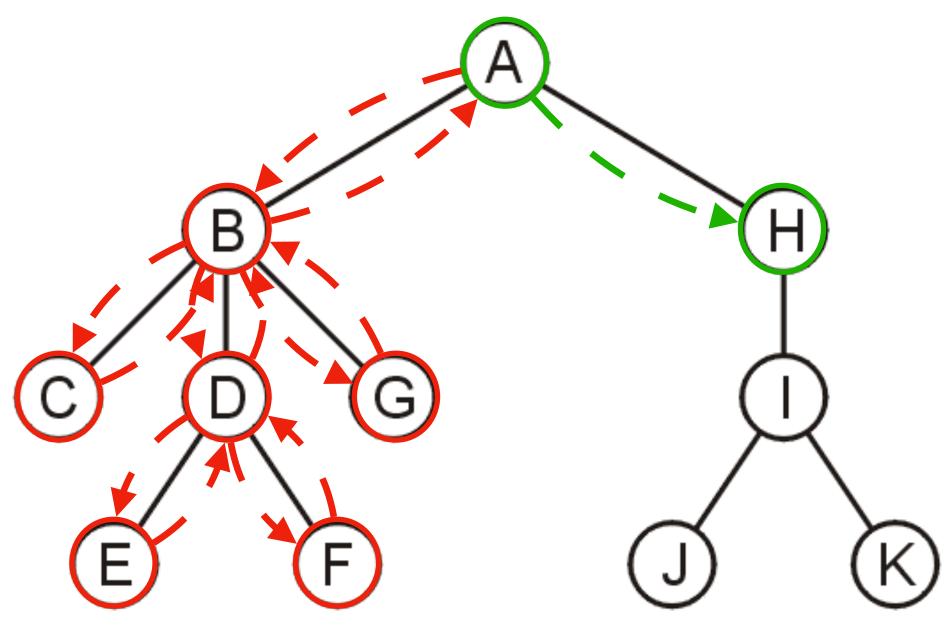


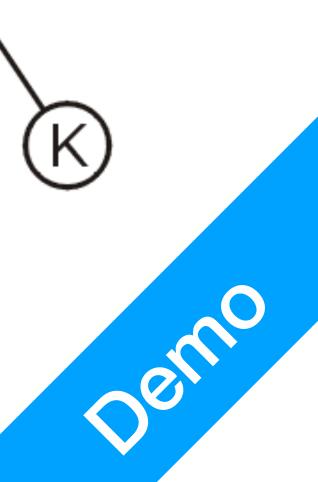




#### • Push H



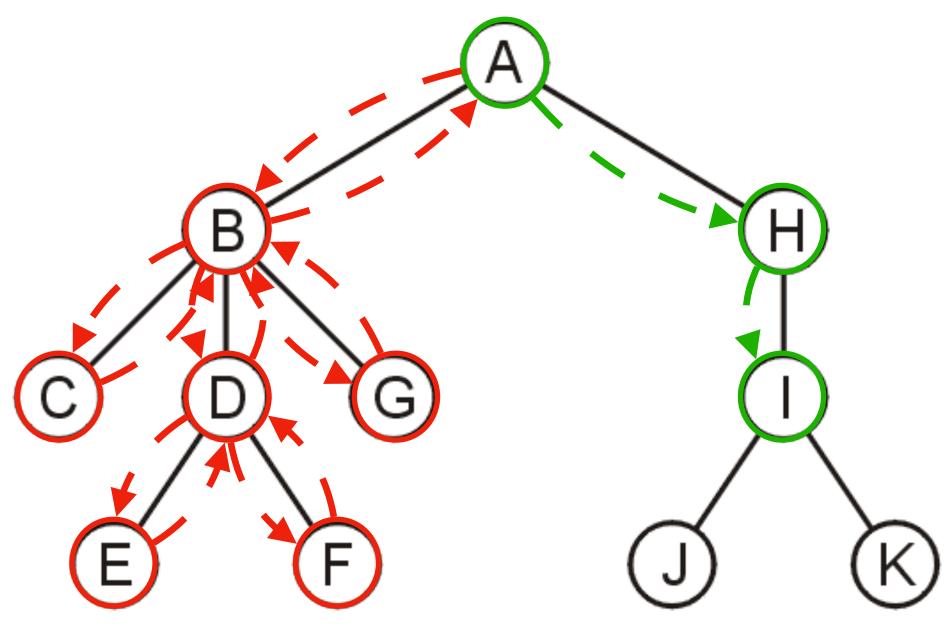


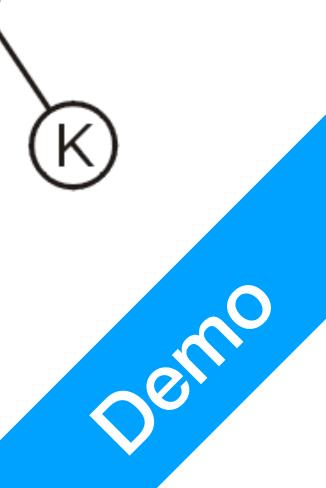




#### • Push I



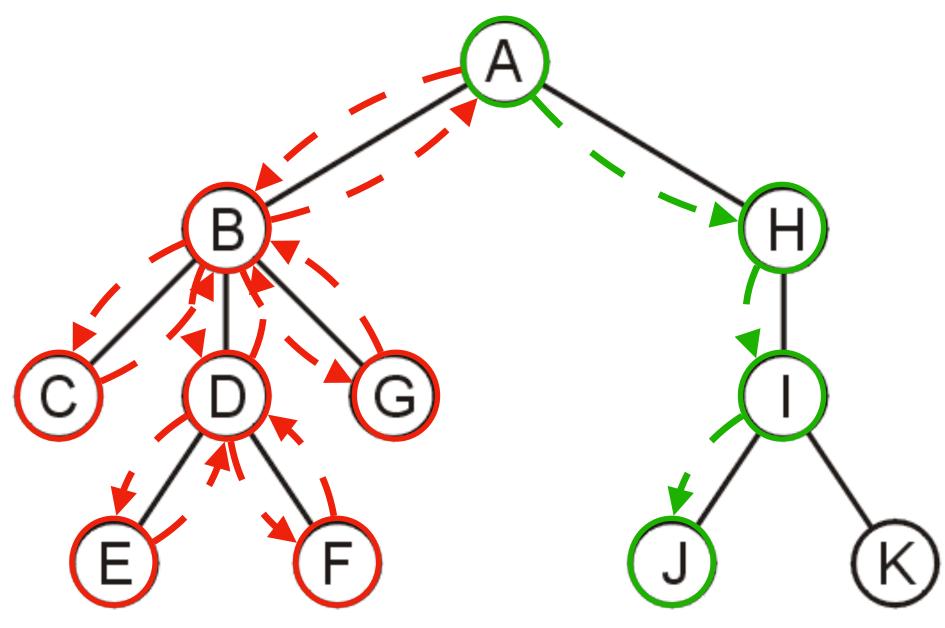


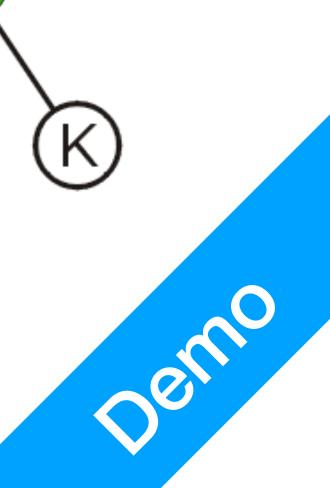




#### • Push J



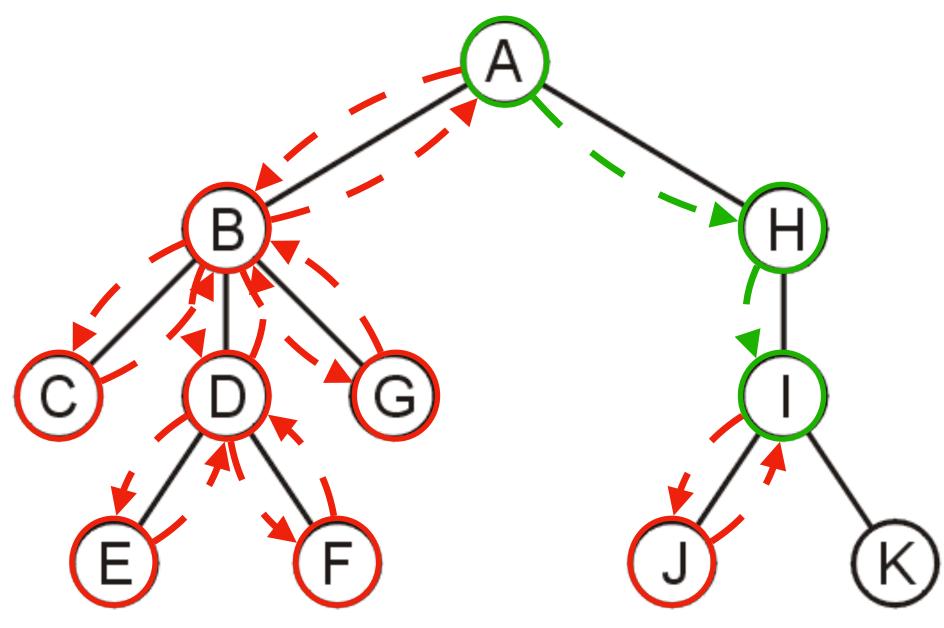


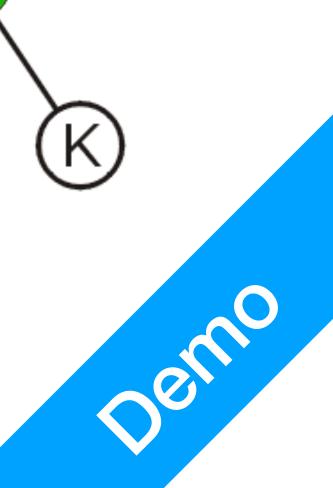




#### • Pop J, go back to I



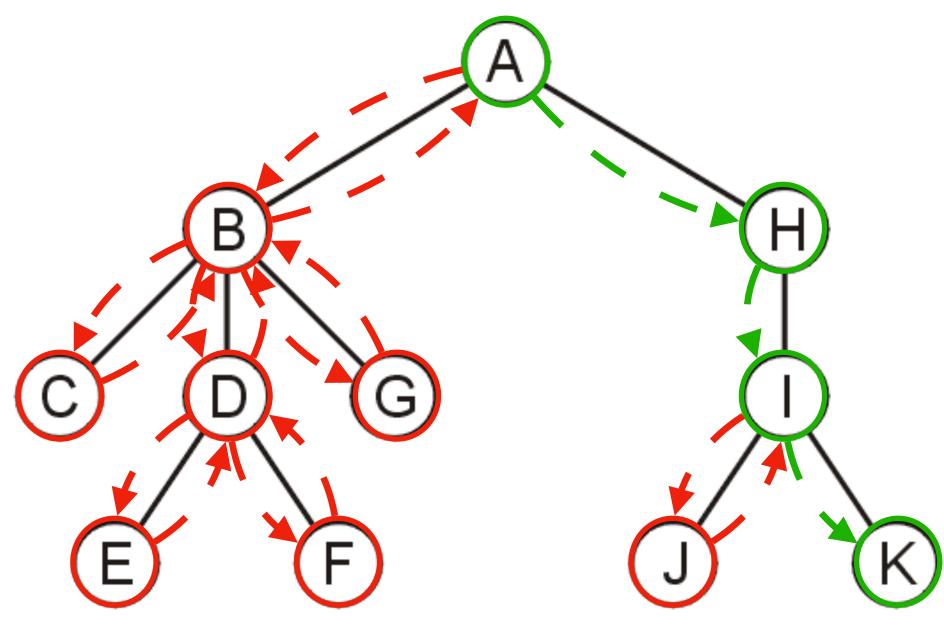


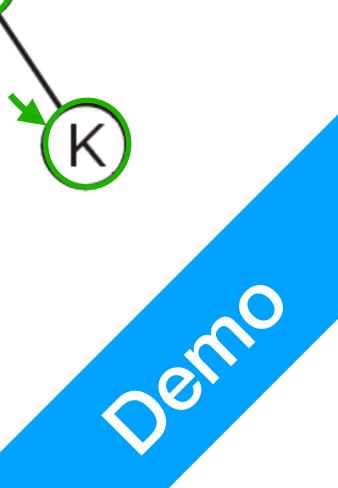




#### • Push K



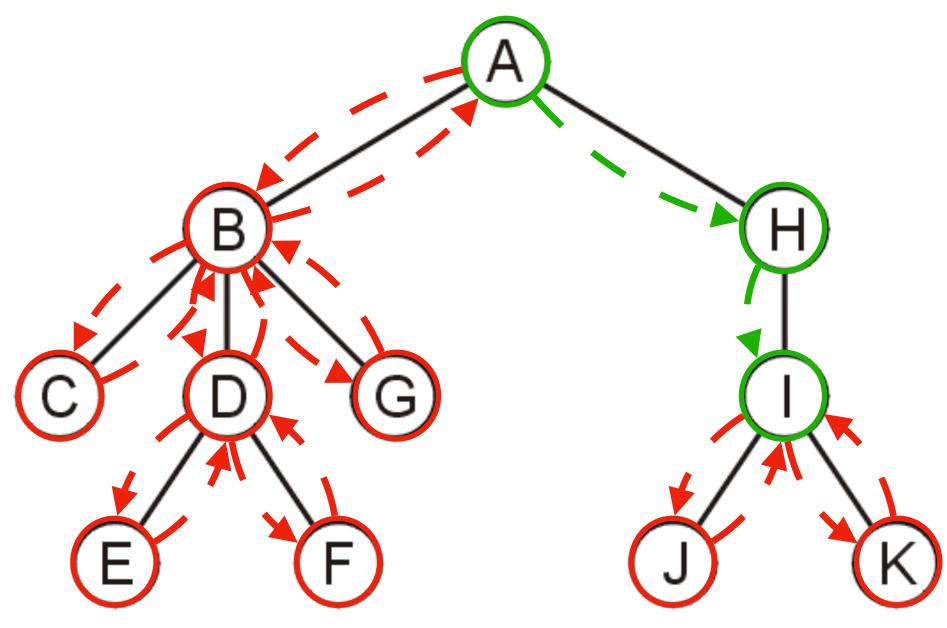


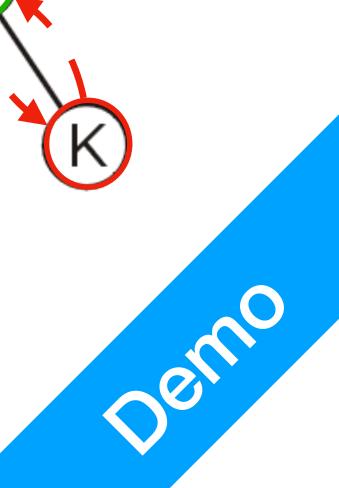




#### • Pop K, go back to I



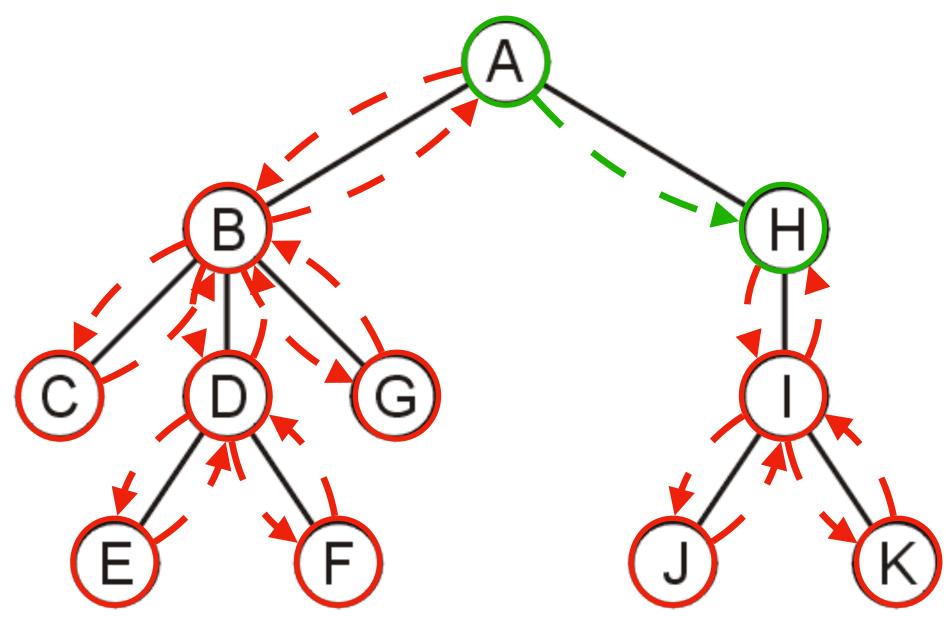


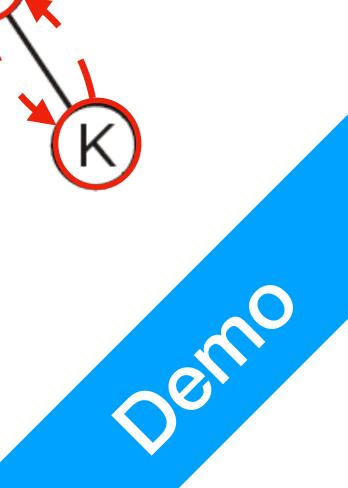




#### • Pop I, go back to H



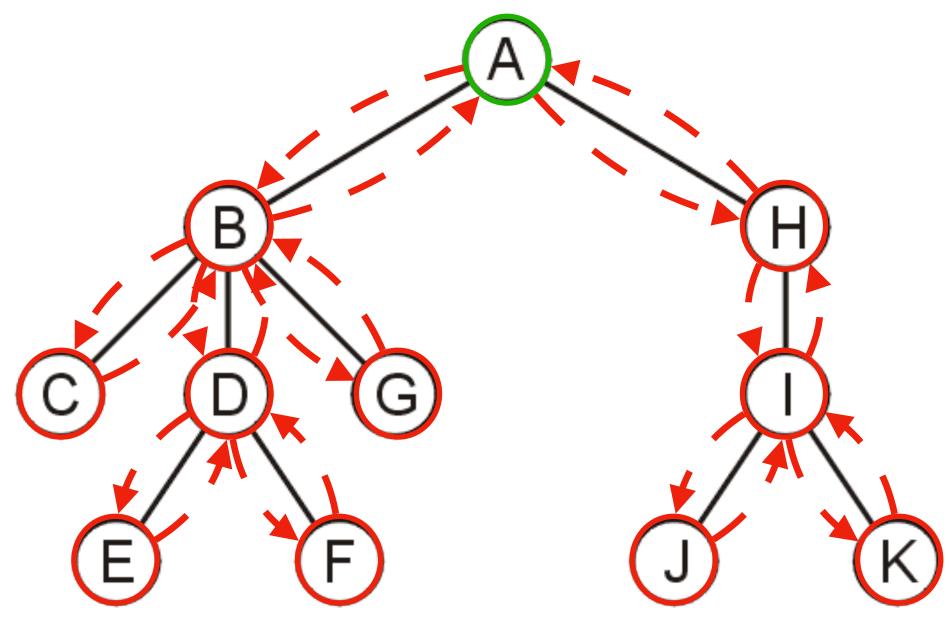


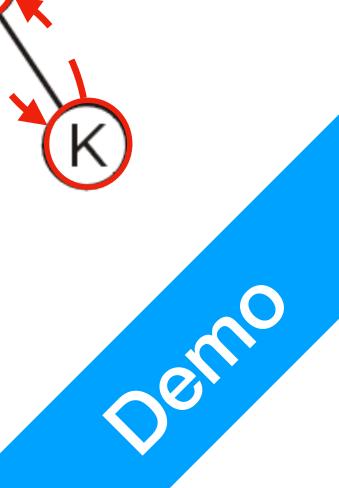




#### • Pop H, go back to A





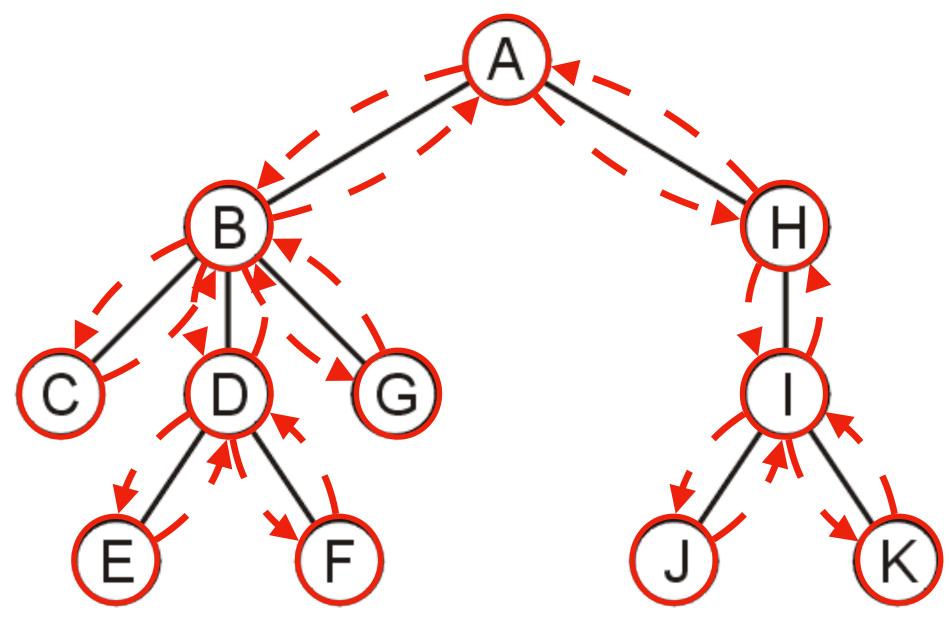


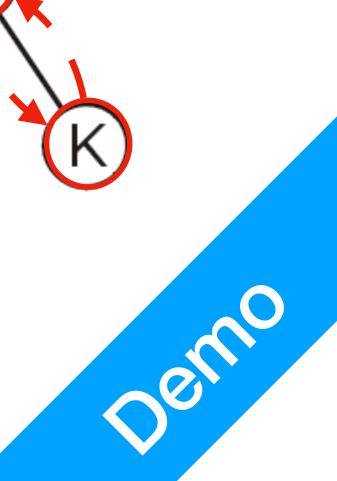




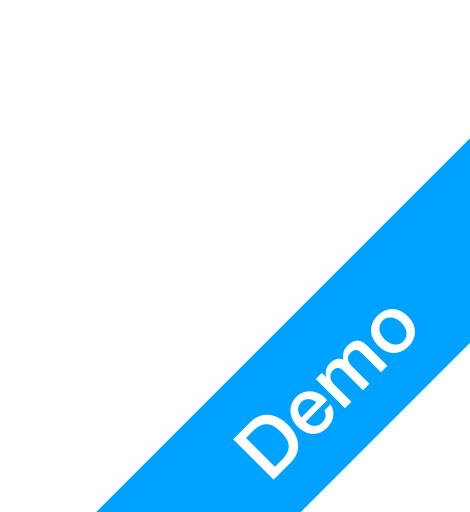
- Pop A, traversal completed
- Traversal Sequence A-B-C-D-E-F-G-H-I-J-K

#### **DFS** Tree

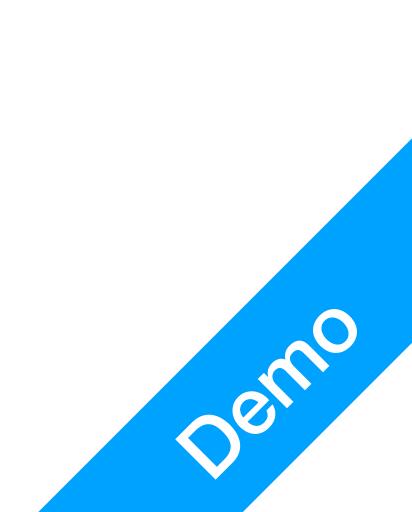




P1 Searching

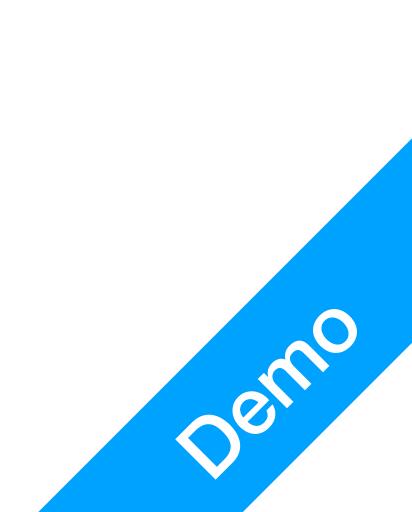




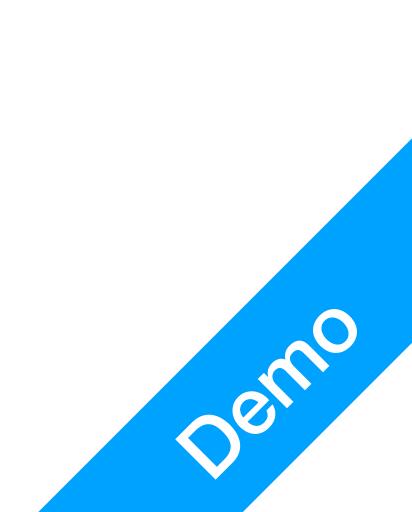


## **DFS Tree Analysis**

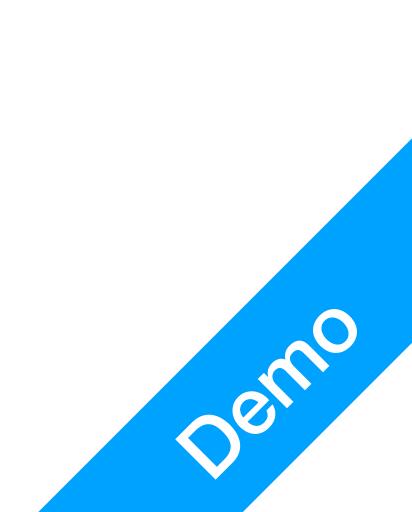
- - Time complexity: O(N + M)



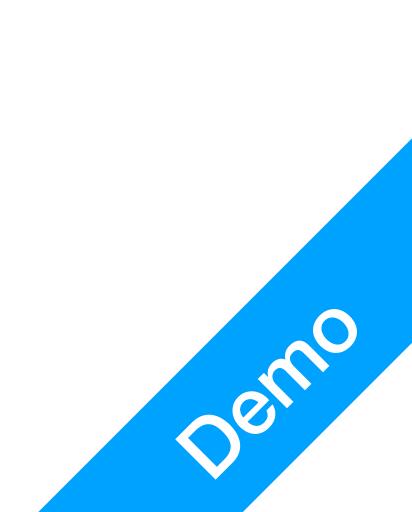
- - Time complexity: O(N + M)
    - Is it  $\Theta(N + M)$  as well? Why?



- - Time complexity: O(N + M)
    - Is it  $\Theta(N + M)$  as well? Why?
  - Space complexity:  $\Theta(N + M)$



- - Time complexity: O(N + M)
    - Is it  $\Theta(N + M)$  as well? Why?
  - Space complexity:  $\Theta(N+M)$ 
    - Is it  $\Theta(N + M)$  as well? Why?



### DFS Example

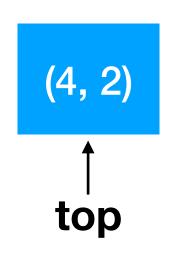
- Village of the Sorcerer
  - Certain areas of the map are not reachable (fences, houses)
  - Certain areas might be entirely blocked off by fences
  - +: player
  - Light Red: player accessible regions

\*\*\*\* # # \*\*\*## # 

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- We start by initialising a Stack to store coordinates
- push(playerCoordinate), which is 4,2
  - push((4,2));
  - In C++, you can simulate this using 2 int-based stacks



1 2 3 0 4 \* # 0 # # # # # 1 # # # 2 # # 3 # # 毌 4 # # 5





• top() = 
$$(4, 2);$$

	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#				#
4	#		<b>+</b>	#	#
5		#		#	





• top() = 
$$(4, 1);$$

		_			
	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#		#		#
3	#	Ť			#
4	#	←	<b>_</b>	#	#
5		#		#	





• top() = 
$$(3, 1);$$

	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#	Ť	#		#
3	#				#
4	#	←	-+	#	#
5		#		#	





• top() = 
$$(2, 1);$$



	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#	Ť	#		#
3	#				#
4	#			#	#
5		#		#	





• top() = 
$$(3, 1);$$

	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#	Ť	#		#
3	#	 			#
4	#	←		#	#
5		#		#	





• For every frontal element, traverse randomly until cannot further

• top() = 
$$(3, 2);$$

• push(3,3)

	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#	ſ	#		#
3	#	 			#
4	#			#	#
5		#		#	





• For every frontal element, traverse randomly until cannot further

• top() = 
$$(3, 3);$$

• push(2,3)

	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#	Ť	#	Ť	#
3	#				#
4	#	←	-+	#	#
5		#		#	

(4, 2)



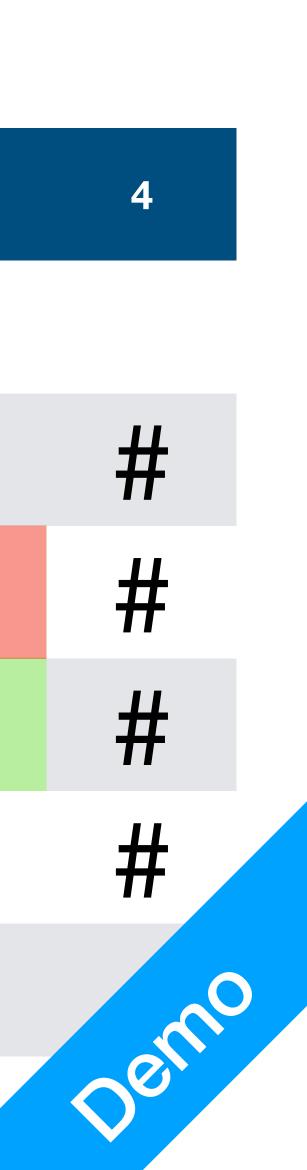


• For every frontal element, traverse randomly until cannot further

• top() = 
$$(2, 3);$$

• pop()

	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#	ſ	#		#
3	#	 		<b>&gt;</b>	#
4	#		-+-	#	#
5		#		#	





• top() = 
$$(3, 3);$$

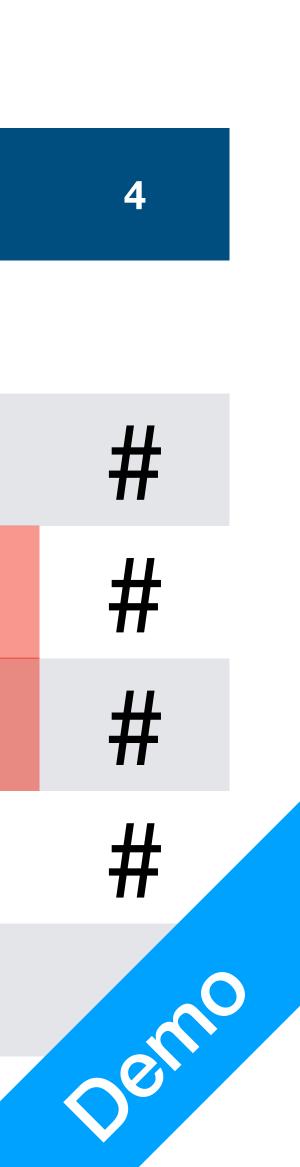
	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#	ſ	#	ſ	#
3	#	 	<b>→</b>		#
4	#		+	#	#
5		#		#	





• top() = 
$$(3, 2);$$

	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#	Ť	#	<b>↑</b>	#
3	#	│ ↑	<b>→</b>	<b>→</b>	#
4	#	 ▲	-+-	#	#
5		#		#	





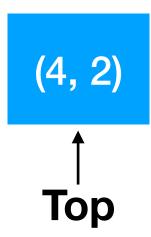
• top() = 
$$(3, 1);$$

	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#	ſ	#	ſ	#
3	#				#
4	#	▲	<b>_</b>	#	#
5		#		#	





• top() = 
$$(4, 1);$$

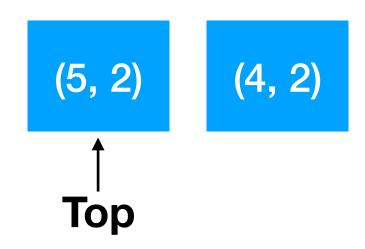


	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#	Ť	#	ſ	#
3	#		<b>→</b>	<b>▶</b>	#
4	#		-+-	#	#
5		#		#	

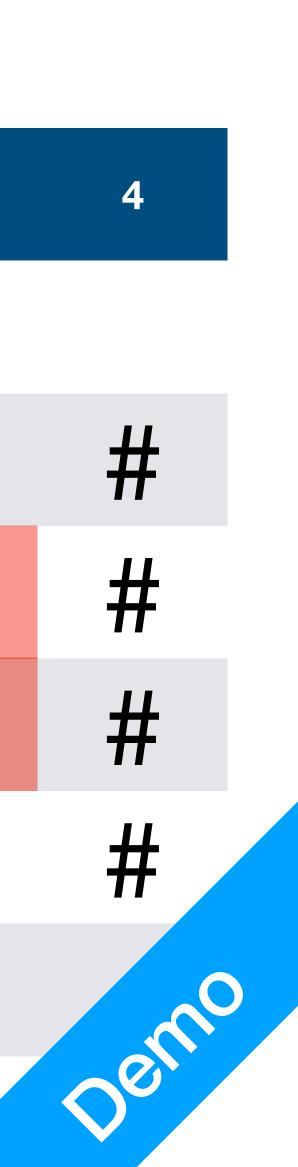




• top() = 
$$(4, 2);$$

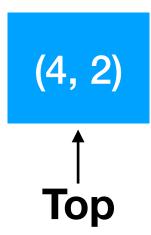


	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#	Ť	#	ſ	#
3	#	│ 	► —	►	#
4	#			#	#
5		#		#	





• top() = 
$$(5, 2);$$



	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#	Ť	#	ſ	#
3	#	│ 	► —	<b>▶</b>	#
4	#			#	#
5		#		#	



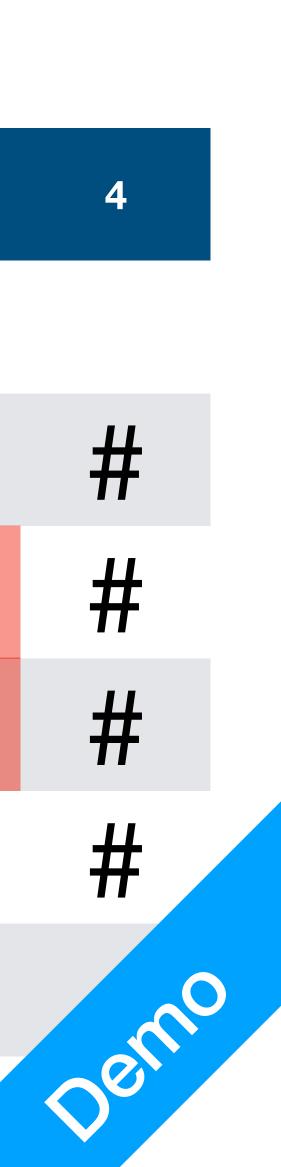


• For every frontal element, traverse randomly until cannot further

• top() = 
$$(4, 2);$$

• pop()

	0	1	2	3	4
0	*	#			
1	#	#	#	#	#
2	#	Ť	#	ſ	#
3	#	│ 			#
4	#		<b>_</b> _	#	#
5		#		#	

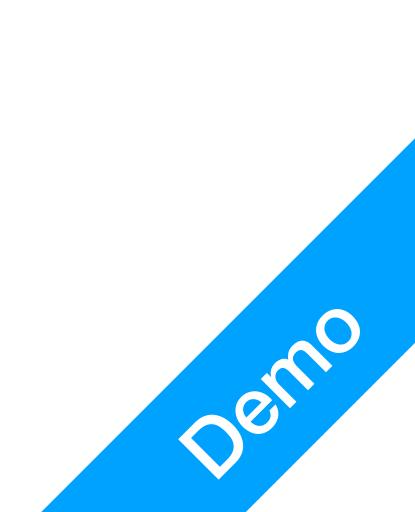


P1 Searching



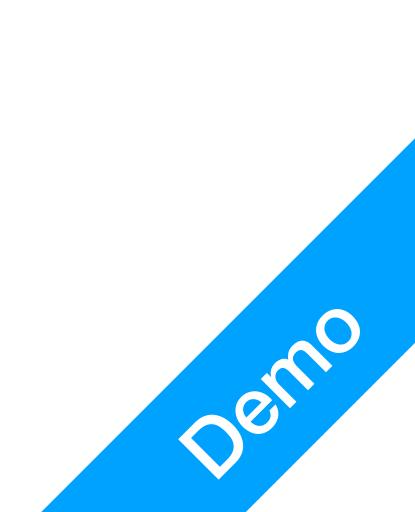


#### • Assuming map size $N \times M$ , what is the time and space complexity?

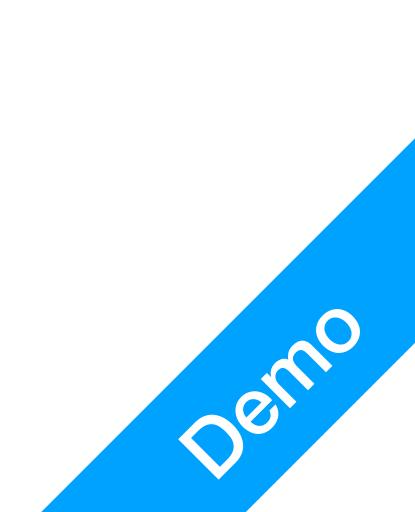




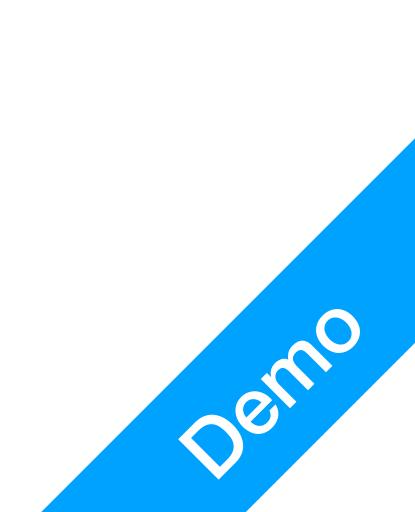
- Assuming map size  $N \times M$ , what is the time and space complexity?
  - Time complexity:  $O(N \times M)$



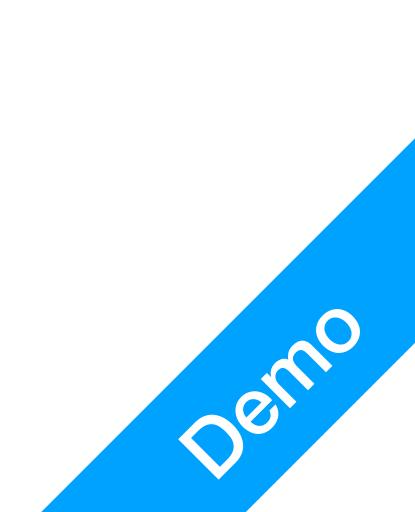
- Assuming map size  $N \times M$ , what is the time and space complexity?
  - Time complexity:  $O(N \times M)$ 
    - Is it  $\Theta(N \times M)$  as well? Why?



- Assuming map size  $N \times M$ , what is the time and space complexity?
  - Time complexity:  $O(N \times M)$ 
    - Is it  $\Theta(N \times M)$  as well? Why?
  - Space complexity:  $O(N \times M)$



- Assuming map size  $N \times M$ , what is the time and space complexity?
  - Time complexity:  $O(N \times M)$ 
    - Is it  $\Theta(N \times M)$  as well? Why?
  - Space complexity:  $O(N \times M)$ 
    - Is it  $\Theta(N \times M)$  as well? Why?





## Summary

- Lecture 7: Data Structure 1-4
  - Linked List
  - Stack
  - Queue
  - $\Theta$  and Big-O Notation
  - BFS, DFS

