

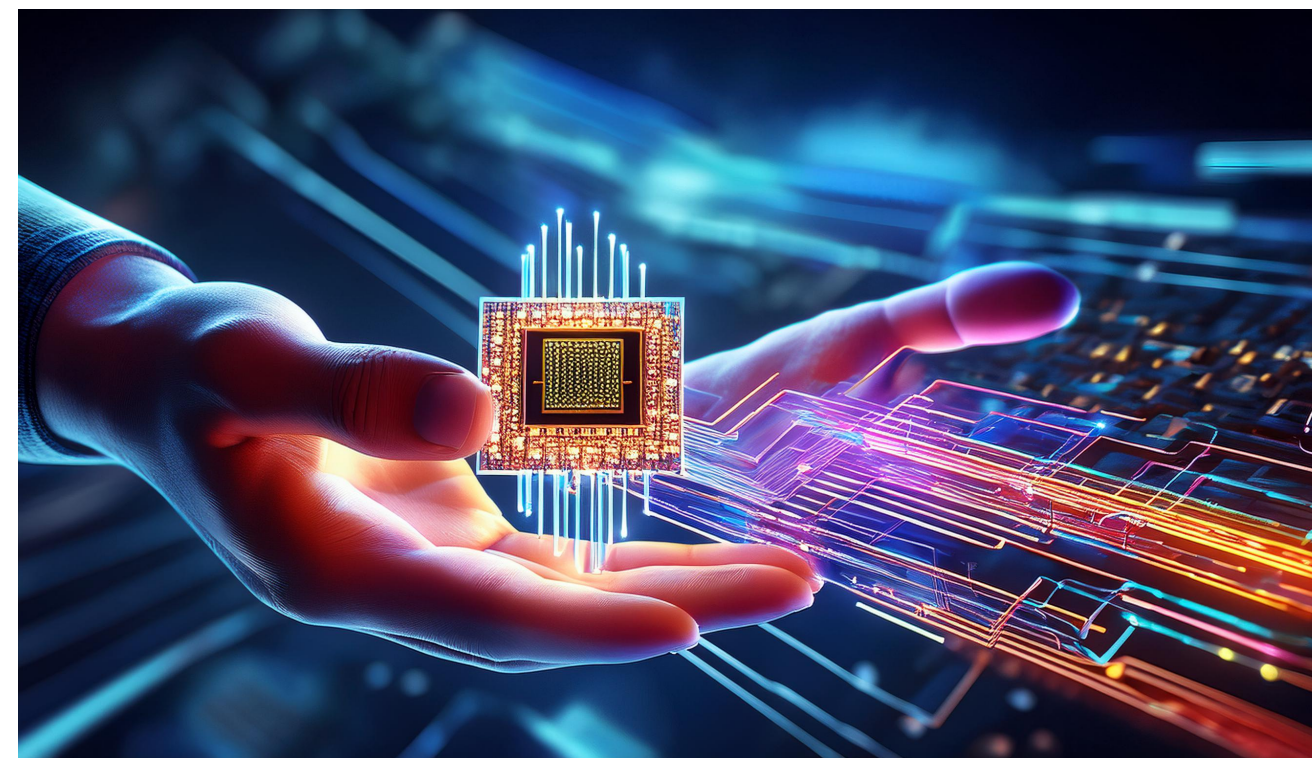


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CSCI 250

Introduction to Computer Organisation

Lecture 5: Compiler Basics III



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2024 Fall Semester (S3)

Overview

- Architecture: von Neumann
- Textbook: CO: 4.5
- Core Ideas:
 1. Assembler Requirement

Lab 5

Assembler Requirement

Assembler Directives

- Your assembler will support 1 directive, `.global`
- This line could appear anywhere in the assembly code, except for within the definition of a symbol
- Main function must be defined using `.global as _main`

Symbols

- Your assembler will the definition of symbols
 - `_main` is mandatory
- Your assembler should also support other symbols, so your programmer can define other functions. Your programmer could try to name the symbol anything, but it has to meet the requirement for variable names for other programming languages
 - Exception: `x0-x6` or `X0-X6` should be reserved for register names
- Literal numbers need to be supported, including Hex and Bin. See LS17 for detail.

B Instruction

- B/BL is the only way for the programmer to change PC (R7)'s value
Your assembler should prevent PC's value from being changed by other instructions, including by the programmer using MOV
- BL is not in the list of instructions that your CPU need to support, however your assembler will support it, by
 - Saving current PC to R6 (LR: Link Register) using MOV
 - Use B to branch to target function, after its finished execution,
 - Use MOV to go back to original PC stored in R6 (e.g. main function)

Assembler Output

```
$ python3 asm_arm16.py programme.s -o programme.ic  
$ ./asm_arm16 programme.s -o programme.ic
```

- Our development target is your ARM16 CPU computer, so your assembler should output in a way such that it can be loaded into the instruction cache of your ARM16 CPU.
- Your assembler will take 1 mandatory argument for the input filename (e.g. `programme.s`), and 1 optional flag `-o` for specifying the output filename
- Your assembler can be programmed using Python3 or C++
- How do you test it? You need to be able to copy the assembler's output to the instruction cache, and see it running.